# **SIEMENS**







**OPERATING INSTRUCTIONS** 

# SINAMICS

# **SINAMICS IOP-2**

Intelligent Operator Panel 2 Intelligent commission and configuration tool

# SIEMENS

# Intelligent Operating Panel 2 (IOP-2)

**Operating Instructions** 

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Edition 09/2022, Firmware IOP-2 V2.7 SP1

### Legal information

### Warning notice system

This manual contains notices you have to observe in order to ensure your personal safety, as well as to prevent damage to property. The notices referring to your personal safety are highlighted in the manual by a safety alert symbol, notices referring only to property damage have no safety alert symbol. These notices shown below are graded according to the degree of danger.

### A DANGER

indicates that death or severe personal injury will result if proper precautions are not taken.

### 🕂 WARNING

indicates that death or severe personal injury may result if proper precautions are not taken.

### $\bigwedge$ CAUTION

indicates that minor personal injury can result if proper precautions are not taken.

#### NOTICE

indicates that property damage can result if proper precautions are not taken.

If more than one degree of danger is present, the warning notice representing the highest degree of danger will be used. A notice warning of injury to persons with a safety alert symbol may also include a warning relating to property damage.

### **Qualified Personnel**

The product/system described in this documentation may be operated only by **personnel qualified** for the specific task in accordance with the relevant documentation, in particular its warning notices and safety instructions. Qualified personnel are those who, based on their training and experience, are capable of identifying risks and avoiding potential hazards when working with these products/systems.

### **Proper use of Siemens products**

Note the following:

### M WARNING

Siemens products may only be used for the applications described in the catalog and in the relevant technical documentation. If products and components from other manufacturers are used, these must be recommended or approved by Siemens. Proper transport, storage, installation, assembly, commissioning, operation and maintenance are required to ensure that the products operate safely and without any problems. The permissible ambient conditions must be complied with. The information in the relevant documentation must be observed.

### Trademarks

All names identified by <sup>®</sup> are registered trademarks of Siemens Aktiengesellschaft. The remaining trademarks in this publication may be trademarks whose use by third parties for their own purposes could violate the rights of the owner.

### **Disclaimer of Liability**

We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.

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# Changes in this manual

### Changes to this manual - Edition 09/22

Listed below and the specific changes that have been incorporated in this new version of the IOP-2 Operating Instructions.

### Changes

- The Jog function in the Control Menu as been updated: Jog (Page 43)
- I/O simulation guidance has been updated in the Diagnostics Menu: Diagnostics (Page 52)

# **Fundamental safety instructions**

### 2.1 General safety instructions

### MARNING WARNING

#### Danger to life if the safety instructions and residual risks are not observed

If the safety instructions and residual risks in the associated hardware documentation are not observed, accidents involving severe injuries or death can occur.

- Observe the safety instructions given in the hardware documentation.
- Consider the residual risks for the risk evaluation.

### 

### Malfunctions of the machine as a result of incorrect or changed parameter settings

As a result of incorrect or changed parameterization, machines can malfunction, which in turn can lead to injuries or death.

- Protect the parameterization against unauthorized access.
- Handle possible malfunctions by taking suitable measures, e.g. emergency stop or emergency off.

### 2.2 Warranty and liability for application examples

Application examples are not binding and do not claim to be complete regarding configuration, equipment, or any eventuality which may arise. Application examples do not represent customer-specific solutions, but merely serve to provide assistance with typical tasks.

As the user you yourself are responsible for ensuring that the products described are operated correctly. Application examples do not relieve you of your responsibility for safe handling when using, installing, operating and maintaining the equipment.

### 2.3 Cybersecurity information

Siemens provides products and solutions with industrial cybersecurity functions that support the secure operation of plants, systems, machines and networks.

In order to protect plants, systems, machines and networks against cyber threats, it is necessary to implement – and continuously maintain – a holistic, state-of-the-art industrial cybersecurity concept. Siemens' products and solutions constitute one element of such a concept.

#### 2.3 Cybersecurity information

Customers are responsible for preventing unauthorized access to their plants, systems, machines and networks. Such systems, machines and components should only be connected to an enterprise network or the internet if and to the extent such a connection is necessary and only when appropriate security measures (e.g. firewalls and/or network segmentation) are in place.

For additional information on industrial cybersecurity measures that may be implemented, please visit

https://www.siemens.com/cybersecurity-industry.

Siemens' products and solutions undergo continuous development to make them more secure. Siemens strongly recommends that product updates are applied as soon as they are available and that the latest product versions are used. Use of product versions that are no longer supported, and failure to apply the latest updates may increase customer's exposure to cyber threats.

To stay informed about product updates, subscribe to the Siemens Industrial Cybersecurity RSS Feed under

https://new.siemens.com/cert.

Further information is provided on the Internet:

Industrial Security Configuration Manual (<u>https://support.industry.siemens.com/cs/ww/en/</u>view/108862708)

### 🔨 WARNING

#### Unsafe operating states resulting from software manipulation

Software manipulations, e.g. viruses, Trojans, or worms, can cause unsafe operating states in your system that may lead to death, serious injury, and property damage.

- Keep the software up to date.
- Incorporate the automation and drive components into a state-of-the-art, integrated industrial cybersecurity concept for the installation or machine.
- Make sure that you include all installed products in the integrated industrial cybersecurity concept.
- Protect files stored on exchangeable storage media from malicious software by with suitable protection measures, e.g. virus scanners.
- Carefully check all cybersecurity-related settings once commissioning has been completed.

# Safety notes

### 3.1 Warnings and cautions

### Warnings and cautions

### ANGER DANGER

### Ensuring a safe and stable state

During commissioning of the converter it is essential to ensure that the system is in a safe and stable state, as some commissioning processes have the potential to start the motor. Therefore it is important to secure any loads and ensure that should the motor start, no potentially dangerous conditions exist.

### \Lambda warning

### The converter will stop if the IOP-2 is removed when in Hand mode

When the IOP-2 is in Hand mode, that is, when the command source is switched to Hand and all OFF and RUN commands are given via the IOP-2 buttons.

When in the Hand mode, if the IOP-2 is removed from the converter, the converter will stop within a few seconds of the IOP-2 being removed.

Before removing the IOP-2, ensure that the IOP-2 is placed in AUTO mode and receiving its command source from the PLC.

### M WARNING

#### Risk of death due to software manipulation when using exchangeable storage media

Storing files onto exchangeable storage media amounts to an increased risk of infection of the commissioning PCs, e.g. with viruses or malware. Incorrect parameter assignment can cause machines to malfunction, which can lead to injuries or death.

• Protect files stored on exchangeable storage media from malicious software using appropriate protection measures, e.g. virus scanners.

### MARNING 🔨

#### Risk of death due to software manipulation when using exchangeable storage media

Storing the parameterization (incl. Safety Integrated parameterization) on exchangeable storage media carries the risk that the original parameterization (with Safety Integrated) will be overwritten, for example, by the IOP-2 of another drive without Safety Integrated. Incorrect parameter assignment can cause machines to malfunction, which can lead to injuries or death.

- Ensure that only the IOP-2 that belongs to the respective converter is used.
- Ensure that only trained or authorized personnel have access to the enclosures, cabinets or electrical equipment rooms.

### 3.1 Warnings and cautions

#### Note

- The IOP-2 can be fitted to and removed from the converter while power is applied.
- The IOP-2 will set the USS PZD (P2012) length to 4 when connected to the converter.

# Overview

### 4.1 Introduction

### Compatibility

The Intelligent Operator Panel 2 (IOP-2) has been designed to enhance the interface and communications capabilities of SINAMICS Inverters.

The IOP-2 connects to the Inverter through an RS232 interface. It has been designed to automatically recognize the following devices from the SINAMICS range:

- SINAMICS G120 CU230P-2
- SINAMICS G120 CU240B-2
- SINAMICS G120 CU240E-2
- SINAMICS G120 CU250S-2
- SINAMICS G120C
- SINAMICS G120D-2 CU240D-2\*
- SINAMICS G120D-2 CU250D-2\*
- SINAMICS ET 200pro FC-2\*
- SINAMICS G110D\*
- SINAMICS G110M\*
- SINAMICS G120X
- SINAMICS G120XA

\*Denotes Control Units that require the IOP-2 Hand-Held Kit and the optical cable to connect the IOP to the Control Unit.

Hand-Held Kit order number: 6SL3255-0AA00-4HA1. Optical cable order number: 3RK1922-2BP00

#### Overview

#### 4.1 Introduction

For information on firmware and language updates, please see Updating the IOP-2 firmware (Page 27).

### Note

### IOP functional support

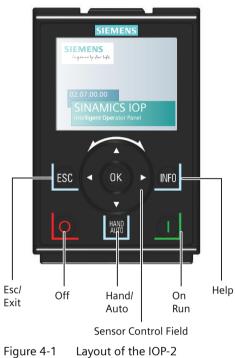
- Drives with SINAMICS firmware 4.7 SP3 or above will support the new commission processes of "Quick Setup" and "Advanced Setup".
- Drives with GP firmware prior to version 3.4 are not fully supported by the IOP-2.
- The actual menu structure and functionality of the IOP-2 will be influenced by the following factors:
  - The software version and type of Control Unit and Power Module to which the IOP-2 is fitted.
  - The firmware and software version of the IOP-2.
  - The selected functional group filtering of the parameters.

### General Data Protection Regulation (GDPR) compliance

Siemens observes the principles of data protection, in particular the principle of data minimization (privacy by design). For this product, the IOP-2, this means: The product does not process / store any personal data, only technical functional data (e.g. time stamp). If the user links this data with other data (e.g. shift plans) or stores personal data on the same medium (e.g. hard disk) and thus establishes a personal reference, the user must ensure compliance with data protection regulations.

## 4.2 Layout and functions

### Overview



The physical layout of the IOP-2 is shown below:

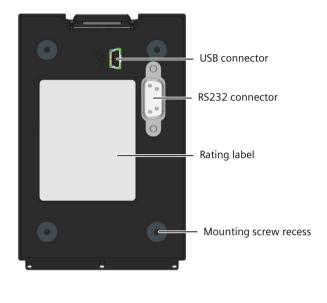


Figure 4-1 Layout of the f

#### Overview

### 4.2 Layout and functions

The IOP-2 is operated by using a Sensor Control Field and five additional buttons. The specific functions of the Sensor Control Field and buttons are shown in the table below.

Table 4-1Function of the IOP-2 controls

Кеу	Function							
	The Sensor Control Field has the following functions:							
( OK) F	• In a menu, sliding your finger around the Sensor Control Field changes the selection.							
	• When a selection is highlighted, pressing the OK button in the centre of the Sensor Control Field confirms the selection.							
	• When editing a parameter, sliding your finger around the Sensor Control Field changes the displayed value clockwise increases the value and anti-clockwise decreases the displayed value.							
	• When editing parameter or search values there is a choice to edit individual digits using the arrow keys or an entire value using the Sensor Control Field. The speed with which you slide your finger around the Sensor Control Field increases or decreases the speed of movement of the cursor.							
	• The Sensor Control Field has integrated arrows which can be used to navigate through the menus and individual digits in the inputs fields.							
	The ON key has the following functions:							
	In AUTO mode can be changed by pressing the HAND/AUTO key.							
	• In HAND mode the converter is started - the converter status icon starts turning.							
	Notes:							
	For Control Units with firmware versions less than 4.0: When running in AUTO mode, HAND mode cannot be selected unless the converter is stopped. For Control Units with firmware versions 4.0 or greater: When running in AUTO mode, HAND mode can be selected and the motor will continue to run at the last selected setpoint speed.							
	When the converter is running in HAND mode, the motor stops when switched to AUTO.							
	The OFF key has the following functions:							
	• If pressed for longer than 3 seconds the converter will perform an OFF2; the motor will then coast down to a standstill. Note: 2 presses of the OFF key within 3 seconds will also perform and OFF2.							
	If pressed for less than 3 seconds the following actions will be performed:							
	<ul> <li>If in AUTO mode the screen will display an information screen stating that the command sources is AUTO and can be changed using the HAND/AUTO key. The converter will not be stopped.</li> </ul>							
	<ul> <li>If in HAND mode the converter will perform an OFF1; the motor will come to a standstill in the ramp-down time set in parameter P1121.</li> </ul>							
	The ESC key has the following functions:							
ESU	• If pressed for less than 3 seconds the IOP-2 returns to the previous screen or if a value has been edited, the new value is not saved.							
	• If pressed longer than 3 seconds the IOP-2 returns to the status screen.							
	When using the ESC key in the parameter editing mode, no data is saved unless the OK key is pressed first.							

Кеу	Function
	The INFO key has the following functions:
INFO	Displays additional information for the currently selected item.
	Pressing the INFO key again will display the previous screen.
	• Pressing the INFO key for >= 2 seconds will display the "Footer Symbol Guide" with more icon descriptions on
	most screens.
HAND	The HAND/AUTO key switches the command source between HAND and AUTO mode.
AUTO	HAND sets the command source to the IOP-2.
	AUTO sets the command source to an external source, for example, fieldbus.
	Note: When switching from the HAND mode back to the AUTO mode, the setpoint screen will change back to the standard status screen.

### Locking and unlocking the keypad

The keypad can only be locked once the power-up cycle has been completed. If the keys are activated before the power-up cycle is completed, the IOP-2 will enter the DEMO mode.

To lock the IOP-2 keypad press **ESC** and **INFO** simultaneously for 3 seconds or more. To unlock the keypad press **ESC** and **INFO** simultaneously for 3 seconds or more.

### 4.3 Screen icons

### Overview

The IOP-2 displays a number of icons at the top right-hand edge of the display to indicate various states or current conditions of the converter. These icons are explained in the table below.

Function	lcon	Remarks
Command source	**	Auto - the converter receives the command signals from the network con- troller
	JOG	Displayed when the JOG function is active
	<b>S</b>	Hand - the converter is under control of the IOP-2
Inverter status		
		Icon rotates when the motor is running
Fault pending		
Alarm pending		

Table 4-2 Screen icons

#### Overview

### 4.3 Screen icons

Function	lcon	Remarks
Saving to RAM		Indicates that all recent changes to parameters have been saved in RAM only. In the event of a power failure, then all recent changes saved to RAM will be lost. To prevent loss of parameter data a RAM-to-ROM save must be performed.
PID autotuning	~	
Hibernation mode	Φ	
Write Protection	×	Parameters cannot be modified.
Know How Pro- tection		Parameters cannot be viewed or modified.
ESM		Essential Services Mode
Battery condi- tion		The battery status is only shown when the IOP-2 Hand-held kit is used.

### Screen faults and alarm indicators

When a fault or an alarm is active on the converter the top label on the screen will change. The top label will remain red until the fault or warning has been acknowledged or rectified.

oon Status	н. -	oon Sta	tus		AX	⊕₼	
Actual speed	0 rpm	Actual speed			0 rpm		
-1500 Actual speed	1500 <b>0 V</b>	-1500			1500 0 V		
Actual speed	0 0	Actual speed			0 0		
0	1000	0				1000	
 ☆   討   ₩	Ϋ. 😑	õ	ŧĿŧ	Ŷsw	Ų,		

Figure 4-2 Fault and alarm notifications

### Use of screen colours

A brief explanation of the use of the different colours on the screen is given below:

- **Red** Error status: Indicates a fault is active and the Control Unit is in an error condition.
- White Neutral status: The IOP-2 has no connection to the Control Unit.
- **Green** Run status: The converter is running with no active faults. Active alarms will be displayed on the status bar.
- **Blue** Blue denotes the selected item on the screen.

### 4.4 Menu structure

### Overview

The Menu structure of the IOP-2 is shown in the figure below.

### NOTICE

### Variation of menu structure

The structure and content of the menus will vary depending on the firmware version of the IOP-2 and the Control Unit and Power Module to which the IOP-2 is attached.



Denotes additional menus

Figure 4-3 IOP-2 menu structure

Overview

4.4 Menu structure

# Installation

### 5.1 Fitting the IOP-2

### Fitting the IOP-2 to the Control Unit

#### Note

### **IOP-2** power supply

The IOP-2 has no internal power supply and derives its power directly from the Control Unit of the converter through the RS232 interface. The IOP-2 can also be connected to a PC and derives its power through the USB connection.

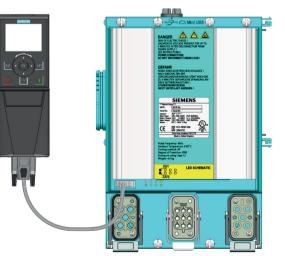
To fit the IOP-2 to the converter Control Unit the following procedure should be performed:

- 1. Place the bottom edge of the IOP-2 casing into the lower recess of the Control Unit housing.
- 2. Push the IOP-2 forward until the top fastening clicks into place on the Control Unit housing.

To use the IOP-2 with a decentralized drive, for example an ET200pro FC-2, an IOP-2 Handheld kit is required and an optical cable. The IOP-2 Handheld kit and optical cable are fitted as shown in the following figure.

The order details of both the IOP-2 Handheld kit and the optical cable are given in the Introduction (Page 11).





IOP Handheld Kit and ET200pro FC-2

Figure 5-1 Fitting IOP-2 on CU and ET200pro FC-2

5.2 Initial set-up

### 5.2 Initial set-up

### Initial set-up sequence

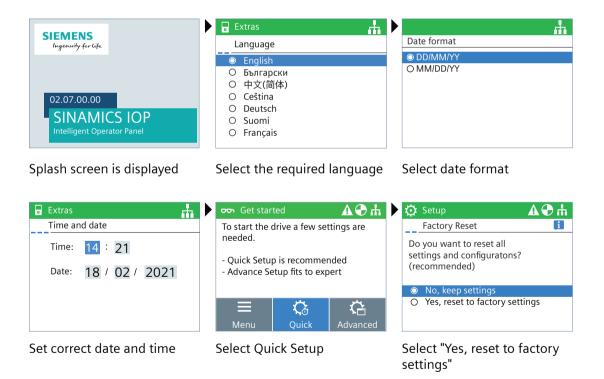
Once the IOP-2 is fitted and powered-up it will automatically detect the type of Control Unit and Power Module to which it has been fitted. On first-time use, the IOP-2 automatically displays the option to select the default language and allow the time and date to be set (if the Control Unit to which the IOP-2 is fitted has a real-time clock). The IOP-2 will then display the choice between "Quick Setup" or Advanced Setup"; "Quick Setup" is the recommended selection. The procedure is outlined below.

### Note

### Saving and cloning of the IOP-2 configuration data

All changes made to an IOP-2 configuration, included all saved parameter sets, are stored in the IOP-2 file structure in the "user" folder.

To copy/clone all this data to another, or multiple IOP-2s, the procedures are shown in Customer parameter sets (Page 71).



### 5.2 Initial set-up

🔅 Drive factory reset 🛛 🛕 🕒	🕂 🕨 🔅 Setup	₽₽₽₽₽	Status	
In progress please wait	Quick Setup	<b>ji</b>	Actual speed	0 rpm
in progress please wait	Motor Standard	IEC (50 HZ, SI)	Actual speed	0 ipin
	Motor Type	Induct	-1500	1500
	Supply Voltage	Supply Voltage 400 V		
	Motor Current	5.90 Arms	Actual speed	0 V
	Motor Power	2.20 kW		
	Motor Speed	1425.00 rpm	0	1000
	Motor Voltage	400 Vrms		
	←ESC ×ESC <sub>2s</sub>	✓OK BOK <sub>2s</sub>	🔅 👬 💘	♥,   =

Wait until the factory reset is finished

# Change or confirm settings

Status screen on completion

### Note

The IOP-2 is delivered with all available languages and the Quick Setup and Advanced Setup functions. For information on Firmware upgrades, please see firmware (Page 27).

The status screen can be reconfigured to show a number of different views and types of values; these can be configured using the "Status Screen Setup" in the "Extras" menu, see  $\square$  Extras Menu (Page 76).

### Language selection

The IOP-2 on first start-up will display the language screen for the user to select their required language, should you wish to select your language manually, the following actions should be performed:

ण्ज Status	▶	📕 Menu		<b>•</b> #	Extras	цц.
Actual speed 	<b>0 rpm</b> 1500	Ö.	⊨  ⊨   ■   Parameters	Diagnostics	Status-screen setup Drive identity Parameter settings Panel settings	Þ
Actual speed	0 V 1000	Setup	Support	Diagnostics C Extras	runer settings	
Select Menu		Select Ext	ras		Select Panel set	
👼 Extra	<u></u>	Extras			🗢 Status	
Panel settings Language Time and date settings Operator panel factory reset Display backlight Lighting duration	Þ	Language ● English ● Българ ● 中文(简 ● Ceština ● Deutscl ● Suomi ● Françai	ски [ф) h		Actual speed -1500 Actual speed 0	0 rpm 1500 0 V 1000
Select language		Select req	uired lang	guage	Press and hold c Status Screen	lown ESC for

All available languages are delivered with the IOP-2.

### Setting time and date

When the IOP-2 is first fitted to a Control Unit, which has a real-time clock, it will automatically display the time and date screen. Should you wish to manually set the time on the IOP-2, the following actions should be performed:

😎 Status	H.	🗮 Menu		• •		Extras	rta -
Actual speed -1500 Actual speed 0	0 rpm 1500 0 V 1000	Setup	⊨  ⊨ Parameters	Diagnostics		Status-screen setup Drive identity Parameter settings Panel settings	
🌣 👬 🕺 🕏		Up / Download	Support	Extras			
Select Menu		Select Ext	ras		5	Select Panel settings	
Extras	H.	Extras		<u></u> ф		Extras	
Panel settings			date settings			Time and date	
Language Time and date settings		Date format	te			Time: 14 : 21	
Operator panel factory reset Display backlight Lighting duration		Daylight savi				Date: 18 / 02 / 2	021
Select Time and date s	settings	Set the Tir	ne and da	te settings	S	Set time and date	
😎 Status 10:25	<b>.</b>						

10:	:25		<u></u>
			0 rpm
			1500
			0 V
			1000
۲.	₩	Ü	≡
	10:	10:25	

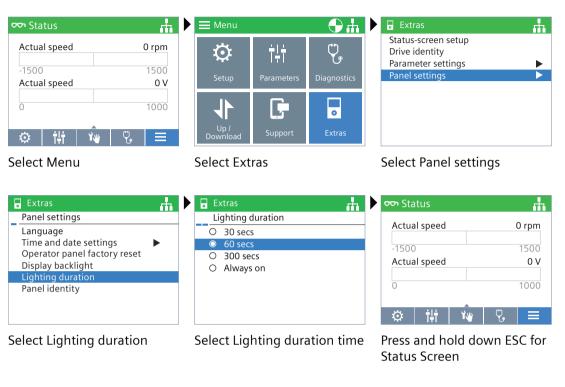
Press and hold down ESC for Status Screen

The settings for time are normally done on the Control Unit if it has a Real-time Clock (RTC). If the Inverter has an RTC the IOP-2 will take its settings from the Control Unit.

5.2 Initial set-up

### **Lighting duration**

To set the length of time that the display remains lit, the following actions should be performed:



### Note

### Screen will flash when an active fault condition exists

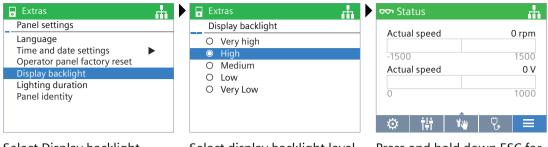
When an active fault condition exists on the IOP-2, the screen will only flash when the IOP-2 is displaying either the status screen or the active fault and alarm screen.

### **Display backlight**

To change the intensity of the backlight, the following actions should be performed:

স্স Status	<b>н</b>	Menu		<b>⊕</b> #	Extras	1
Actual speed -1500 Actual speed	0 rpm 1500 0 V	<b>C</b> Setup	Parameters	Diagnostics	Status-screen setup Drive identity Parameter settings Panel settings	
0	1000	1	C,	0		
© 👬 🕷	ଞ ≡	Up / Download	Support	Extras		
elect Menu		Select Ex	tras		Select Panel settings	

### 5.3 Changing the Status screens



Select Display backlight

Select display backlight level

Press and hold down ESC for Status Screen

The display backlight setting will be automatically changed to the "Low" setting after 60 seconds from the last key press to extend the life of the display. When any key is pressed the backlight setting will automatically return to the user setting.

### 5.3 Changing the Status screens

### Changing the status screens

The status screens of the IOP-2 can show three different styles of screens.

- Bar graph view This shows the selected data on up to two separate sliding bar scales.
- Scalar view This shows the selected data as numerical values in four separate quadrants on the screen.
- Trend view This shows the selected data as two separate real-time plots on the screen.

### Select a different status screen

To select a different status screen the following procedure should be performed:

- 1. When the status screen is displayed, use the UP arrow key to enter the screen selected mode.
- 2. Using the LEFT and RIGHT arrow keys, select the required status screen.
- 3. Press ESC or the DOWN arrow key to accept the new status screen and exit the screen selection mode.

### Modify the display data

To modify the data that is displayed on the status screen, the following procedure should be performed:

- 1. Use the UP key to enter the status screen selection mode.
- 2. Press OK to edit the displayed data.
- 3. Use the arrow keys to navigate around the screen until the data you wish to change is highlighted. Press OK to edit the highlighted data.
- 4. Press OK to edit the parameter to be displayed.
- 5. Select the new parameter you wish to be displayed. Press OK to accept the new selection.

5.3 Changing the Status screens

- 6. The new parameter selection is shown in the list. Press ESC or the DOWN arrow key to return to normal functions of the IOP-2.
- 7. The status screen is shown with the new data values and the screen menu is shown.

An overview of the basic procedures is shown in the figure below.



Figure 5-2

Selecting and modifying the IOP-2 status screens

5.4 User definable labels on status screen

### 5.4 User definable labels on status screen

### User definable labels

User defined labels allow the user to customize the labels that appear on the status screen of the IOP-2.

There are a maximum of four labels that can be defined and they are located on the IOP-2 in the "config" folder. The IOP-2 must be connected to the PC via the USB connection to access the files on the IOP-2. The files are basic text files and can be opened with any basic text editor. The default label names are "default", when the labels have the "default" text, the IOP-2 will ignore the labels. There are the following restrictions when creating your own labels:

- A maximum of 20 characters for each label name.
- The characters that can be used conform to the normal windows file naming conventions.

The four files are named:

- BotLeft.txt
- BotRight.txt
- TopLeft.txt
- TopRight.txt

The file names relate to the area of the status where they will appear.

Simply selected the file you wish to use as a label; open it with a text editor, change the name and then save it back to the same location in the IOP-2 file system. If the file name itself is changed the IOP-2 will not recognize the label.

An example of the status screen with new label names (using all four text files) is shown in the figure below.

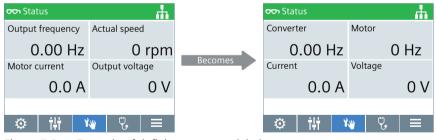


Figure 5-3 Example of defining your own labels

### 5.5 Updating the IOP-2 firmware

### Updating the IOP-2 firmware

The IOP-2 contains firmware, which can be updated by the user by means of a firmware update. To perform the update of the IOP-2 firmware the following steps should be performed.

- 1. Plug the IOP-2 into a PC using the USB connection. Note: Connect the IOP-2 only to an internal USB interface. Do not use an USB interface which is connected to your PC externally (e.g. via a docking station, external USB-Hub or desktop PCs with front sockets).
- 2. The IOP-2 will automatically enter the "Mass Storage" mode.
- 3. Open the file explorer on the PC.
- 4. Navigate to the IOP-2 (removable media). Note: Back up data (e.g., readme, parameter records) that you will need later on the connected PC.
- 5. Format the IOP-2 (do not use quick formatting). Set the size of the allocation units to 2048 bytes (FAT Standard).
- 6. Go to the Service and Support site at the link shown below.
- 7. Download the zip file with the current firmware of the IOP-2 into a folder on the PC and unpack it into a separate directory.
- 8. Copy the downloaded files from the PC directory directly into the IOP-2 folder (the copying process takes approximately 6 minutes).
- 9. When the copying has been completed, wait approximate 5 seconds before disconnecting the IOP-2 from the USB port. The new firmware is now available on the IOP-2 and you can now connect the IOP-2 to a SINAMICS G inverter.

10. When you turn on the SINAMICS G inverter, the IOP-2 will automatically update.

Only IOP-2 firmware update packages obtained through the Siemens Service and Support website at the following link should be used:



IOP-2 firmware download: IOP-2 Firmware update (<u>https://</u> support.industry.siemens.com/cs/ww/en/view/109762019)

### **Reading the OSS License**

The IOP-2 contains open-source software (OSS). The OSS comprises open-source text and satisfies special license terms. If you wish to read the license terms, see: efs/readme\_OSS.zip on the IOP-2.

### Installation

5.5 Updating the IOP-2 firmware

# Setup Menu

### Overview

The IOP-2 Setups are question-driven environment that assist the user to set-up various functions and applications of the converter.

### MARNING WARNING

#### Motor Identification (Motor ID) function will run automatically

Using the "Standard Drive Control" or "Dynamic Drive Control" in Quick Setup, the Motor ID function, if selected, is activated at the end of the commissioning sequence.

The motor identification (motor ID) function, after the completion of the Quick Setup, upon the first startup, will start automatically after approx. 8 to 30 s and accelerate the motor to the setpoint speed.

This action must be taken into account when the Quick Setup procedure has been completed, to ensure that the first ON/RUN command when given for your application, does not produce an unpredicted or unsafe effect on personnel, equipment or premises.

### MARNING WARNING

#### Safe and stable state of the converter

During the setup of the converter it is essential to ensure that the system is in a safe and stable state, as some setup processes have the potential to start the motor. Therefore it is important to secure any loads and ensure that should the motor start, no potentially dangerous conditions exist.

### A CAUTION

#### Default datasets

The Setups use the default Drive datasets (DDS0 and CDS0), if the default datasets are changed to the other datasets, the Setups may not function correctly.

6.1 Example Setups

### 6.1 Example Setups

### **Overview of Setup**

The following examples of how Setup works on the IOP-2 are purely for demonstration purposes only.

### A CAUTION

### Before setting up an application

Prior to using Setup, it is essential that the user's Control Unit and Power Module have been installed and wired correctly, in accordance with the requirements of the user's application. This is extremely important in the case of setting up safety-integrated applications. All inputs and outputs must be defined and configured before any setting up can take place, including the observation and adherence of all local, national and international safety regulations required for the user's application.

### Quick Setup/Advanced Setup

### **Quick Setup**

The Quick Setup procedure is all the user needs to setup the converter quickly and easily. The Quick Setup allows the user to configure the following converter data:

- Motor Standard
- Motor Type
- Supply Voltage
- Motor Current
- Motor Power
- Motor Speed
- Motor Voltage
- Motor Frequency
- Minimum Frequency
- Maximum Frequency
- Ramp-up Time
- Ramp-down Time
- I/O Setup

The default settings of the converter will be automatically read into the IOP-2, but it is recommended that you check that these settings are correct for your converter by comparing the settings with the data from the converter and motor rating labels.

### **Advanced Setup**

The Advanced Setup provides the user with a more comprehensive range of settings that can be configured for specific requirements and applications. The settings that are available are as follows:

- Drive Information: This displays detailed information about the connected Control Unit and Power Module.
- Factory Reset: This allows the converter to be reset to the factory default settings.
- Hardware options: This allows the configuring of an Output Filter and a Braking Resistor.
- Control Type: This allows the selection of the control types, Standard Drive Control, Dynamic Drive Control and Expert. A brief explanation of each Control Type is given below.
- Motor Data: This allows the user to configure the Motor settings which consist of the data presented in the Quick Setup.
- Limit Settings: This gives the user the opportunity to setup the dynamic settings of the converter.
- Optimization: This allows the user to optimize the converter for technological applications and ensure that the correct motor data will be used.
- I/O Setup: The I/O configuration is pre-assigned using macros so that no further settings are necessary. Should the user want to reconfigure the Input and Output settings of the converter, the I/O Setup can be used to perform this function.
- Fieldbus Setup: This allows the user to configure the interface settings.
- Application Setup: This allows the user to configure the application specific functions of the converter.

For more detailed information of the application classes, see the document at the link below:

Application classes (https://support.industry.siemens.com/cs/ww/en/view/109480663)

### **Control Types**

(h

#### **Standard Drive Control**

- Standard Drive Control is preset for the Power Modules PM240, PM240-2 and G120C in frame sizes FSA-C. This application class can, for example, be used for the following applications:
  - Pumps, fans and compressors with flow characteristic
  - Wet or dry beam technology, mills, mixers, kneaders, crushers, agitators
  - Horizontal conveyor technology (conveyor belts, roller conveyors, chain conveyors)
  - Basic spindles

6.1 Example Setups

### **Dynamic Drive Control**

- Dynamic Drive Control is preset for the Power Modules PM240, PM240-2 and PM330 in frame sizes ≥ FSD. This application class can, for example, be used for the following applications:
  - Pumps and compressors with displacement machine
  - Rotary furnaces
  - Extruders
  - Centrifuges

### Expert

• Expert is fixed assigned configuration for the Power Modules PM230, PM250 and PM260 and will soon be available for the G120D, G110M and ET200pro FC-2. This setting corresponds to the existing Setup and will also be assigned to existing projects. It allows the flexible setup of the converter, but requires a detailed understanding of the drive.

### M WARNING

### Motor data identification (motor ID)

When selecting motor data identification (motor ID) with subsequent ramp-up to the setpoint speed (p1900 = 11 or 12; 12 = standard setting based on SINAMICS Firmware V4.7 SP3 with "Standard Drive Control" and "Dynamic Drive Control"), the motor is, upon the first Power ON command, directly accelerated to the setpoint speed, following a short delay time caused by the motor ID (approx. 15 to 30 s). From SINAMICS Firmware V4.7 SP6 the default setting for p1900 = 2.

#### Note

#### Macro source selection

During the Quick Setup process, the user will be presented with a list of preset macros that determine the configuration of the converter. Every Control Unit Operating Instructions contain a list of the macros that are specific for that particular Control Unit and show the wiring configurations for each macro. For further information, see the relevant Operating Instructions.

### **INFO Screens**

INFO Screens (Information Screens) are accessed with a press of the INFO button. There may be multiple INFO screens and you can navigate between each screen using the arrow keys.

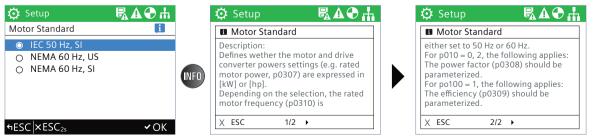


Figure 6-1 Using the INFO button

### 6.1.1 Quick Setup with the IOP-2

NOTICE

### **Quick Setup**

### Requirements prior to using the Quick Setup

- The user must be fully conversant with all safety instructions as detailed in the "Fundamental Safety Instructions" section of the Operating Instructions for your converter.
- The converter must be installed and checked as per the relevant instructions in the "Installation" sections of the converter Operating Instructions.
- Macro source selection: During the Quick Setup process, the user will be presented with a list of preset macros that determine the configuration of converter. Every Control Unit Operating Instructions contain a list of the macros that are specific for that particular Control Unit and show the wiring configurations for each macro. For further information, see the relevant Operating Instructions.
- The information required to be input into the Quick Setup process can be found on the motor rating label, an example of which is included in the Operating Instructions for your converter.
- If the motor is to operate with the "87 Hz characteristic"; You need to use the "Advanced Setup" process and you need to connect the motor in Delta (Δ), this is shown in the "Installation" section of the Operating Instructions for your converter.

স্স Status	<u>њ</u>	🔅 Setup	H D ☉ Setup A 🗨
Actual speed	0 rpm	Quick Setup	Factory Reset
-1500 Actual speed	1500 0 V	Advanced Setup	Do you want to reset all settings and configuratons? (recommended)
0	1000		<ul> <li>No, keep settings</li> <li>Yes, reset to factory settings</li> </ul>
🌣 🛉 👯 🕺	♡,	←ESC ×ESC <sub>2s</sub>	✓ OK
elect Setup		Select Quick Setup	Select Factory Reset (yes or no)

🔅 Drive factory reset 🛛 🛕 🕀 🗗	🕨 🏷 Setup	₣₽ ₽ ₽	🔅 Setup	₷₳₴₼
In progress please wait	Quick Setup	<b>ji</b>	Motor Standard	i
In progress please wait	Motor Standard Motor Type Supply Voltage Motor Current Motor Power Motor Speed Motor Voltage	IEC (50 HZ, SI) Induct 400 V 5.90 Arms 2.20 kW 1425.00 rpm 400 Vrms	<ul> <li>IEC 50 Hz, SI</li> <li>NEMA 60 Hz, US</li> <li>NEMA 60 Hz, SI</li> </ul>	
Factory Reset begins	Select Motor St	✓OK BOK <sub>2s</sub>	<mark>€ESC ×ESC₂s</mark> Select mains freq units	✓OK uency and

#### Setup Menu

### 6.1 Example Setups

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Motor Type	Induct	Motor Type	Induct	O Enter Motor D	
Supply Voltage Motor Current	400 V 5.90 Arms	Characteristic	50 Hz		oue
Motor Power	2.20 kW				
Motor Speed	1425.00 rpm				
Motor Voltage	400 Vrms				
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Select Motor Ty	/pe	Select Input Mo	de	Enter Motor Da	ata or Motor
,		·		Code	
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Quick Setup		Supply Voltage	ļi.	Quick Setup	
Motor Standard Motor Type	IEC (50 HZ, SI) Induct			Motor Standard Motor Type	IEC (50 HZ, SI) Induct
Supply Voltage	400 V		63000 V T	Supply Voltage	400 V
Motor Current	5.90 Arms		00400	Motor Current	5.90 Arms
Motor Power	2.20 kW		1 V ±	Motor Power	2.20 kW
Motor Speed	1425.00 rpm		1 V 1	Motor Speed	1425.00 rpm
Motor Voltage	400 Vrms			Motor Voltage	400 Vrms
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Motor

Motor Voltage

←ESC ×ESC<sub>2s</sub>

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(50 HZ, SI)			
Induct 400 V			2100
5.90 Arms			00
2.20 kW			

ing label

25.00 rpm

400 Vrms

✓OK BOK<sub>2s</sub>

	210000.00 rpm ₹
	001425.20
	0.00 rpm ±
←ESC ×ESC <sub>2s</sub>	✓ OK

Enter Motor Speed from rat-

Supply Voltage Motor Current Motor Power 400 V 5.90 Arms 2.20 kW Motor Speed 1425.00 rpm Motor Voltage 400 Vrms ←ESC ×ESC<sub>2s</sub> ✓OK BOK<sub>2s</sub>

Select Motor Speed

Select Motor Voltage

#### 6.1 Example Setups

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Motor Voltage	ļi	Quick Setup	i	Motor Frequency	i
		Motor Voltage	400 Vrms		
	20000 Vrms <del>T</del>	Motor Frequency	50.00 Hz		650.00 Hz ₹
		Min Freq.	10.00 Hz		
	0400	Max. Freq.	50.00 Hz		050.00
	0 Vrms ±	Ramp-up Time	10.00 s		0.00 Hz ±
	U VIIIIS ±	Ramp-down Time	10.00 s		0.00 HZ ±
		I/O Setup	12		
HESC XESC <sub>2s</sub>	✓ OK	←ESC ×ESC <sub>2s</sub>	✓OK BOK <sup>2s</sup>	←ESC × ESC <sub>2s</sub>	✔ OK

Enter Motor Voltage from rat- Select Motor Frequency ing label

Enter Motor Frequency

🔅 Setup	₣₽₽₽₩	文 Setup
Quick Setup	, i	Min. Freq.
Motor Voltage	400 Vrms	
Motor Frequency	50.00 Hz	
Min Freq.	10.00 Hz	
Max. Freq.	50.00 Hz	
Ramp-up Time	10.00 s	
Ramp-down Time	10.00 s	
I/O Setup	12	
←ESC ×ESC <sub>2s</sub>	✓OK BOK <sub>2s</sub>	←ESC ×ESC <sub>2s</sub>

₿₳₽₼	😥 Setup	₣₽₽₽₩
i	Quick Setup	<b>i</b>
	Motor Voltage	400 Vrms
650.00 Hz ₹	Motor Frequency	50.00 Hz
	Min Freq.	10.00 Hz
010.00	Max. Freq.	50.00 Hz
0.00 Hz ¥	Ramp-up Time	10.00 s
0.00 112 ¥	Ramp-down Time	10.00 s
	I/O Setup	12
✔ OK	←ESC ×ESC <sub>2s</sub>	<b>∕</b> ОК ₿ОК <sub>2s</sub>

Select Min. Freq.

# Enter the required Min. Freq.

Select Max. Freq.

🔅 Setup	₿₳₴₼	Setup	₷∡ዏ₼	Setup	₽ <b>₽</b> ₩
Max. Freq.	ļi	Quick Setup	ļi.	Ramp-up Time	,i
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	7000 Hz ₹	Motor Frequency	50.00 Hz		999999.000 s ₹
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	0.00112 ±	Ramp-down Time	10.00 s		0.000 3 1
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<b>F</b>	wed May Fran	Calast Davis un	T:		

Enter the required Max. Freq. Select Ramp-up Time

Enter required Ramp-up Time

🔅 Setup	₷₳₴₼	🔅 Setup	▙▋ॖ॒	🔅 Setup	₣₽₽₽₩
Quick Setup	<b>i</b>	Ramp-down Time	<b>F</b>	Quick Setup	ļi
Motor Voltage	400 Vrms			Motor Voltage	400 Vrms
Motor Frequency	50.00 Hz		999999.000 s ₹	Motor Frequency	50.00 Hz
Min Freq.	10.00 Hz			Min Freq.	10.00 Hz
Max. Freq.	50.00 Hz		000010.000	Max. Freq.	50.00 Hz
Ramp-up Time	10.00 s		0.000 s ±	Ramp-up Time	10.00 s
Ramp-down Time	10.00 s		0.000 S ±	Ramp-down Time	10.00 s
I/O Setup	12			I/O Setup	12
ᠳESC XESC₂s	✓OK BOK <sub>2s</sub>	SC SC2s	✓ OK	←ESC ×ESC <sub>2s</sub>	<b>∕</b> OK ₿OK <sub>2s</sub>

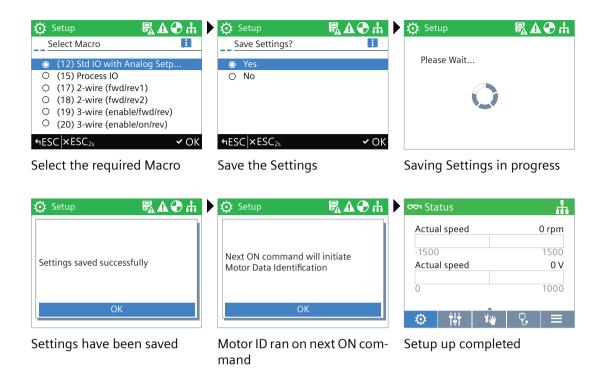
Select Ramp-down Time

Enter required Ramp-down Time

Select I/O Setup

#### Setup Menu

#### 6.1 Example Setups



# 6.1.2 Advanced Setup with the IOP-2

#### Advanced Setup overview

Advanced Setup is a commissioning process for all applications which provides a high degree of flexibility when dealing with the converter settings. The provided settings allow an optimized adaption of the converter to the target application.

The setup process will guide the user through the commissioning process by presenting a number of categories where the user can choose the necessary options and values to commission the converter and motor.

At the conclusion of the setup process, the data can be saved to the converter's memory.

#### Setup Icons

The setup process uses a number of very important icons to indicate the status of the settings. A description of the various icons is given below.

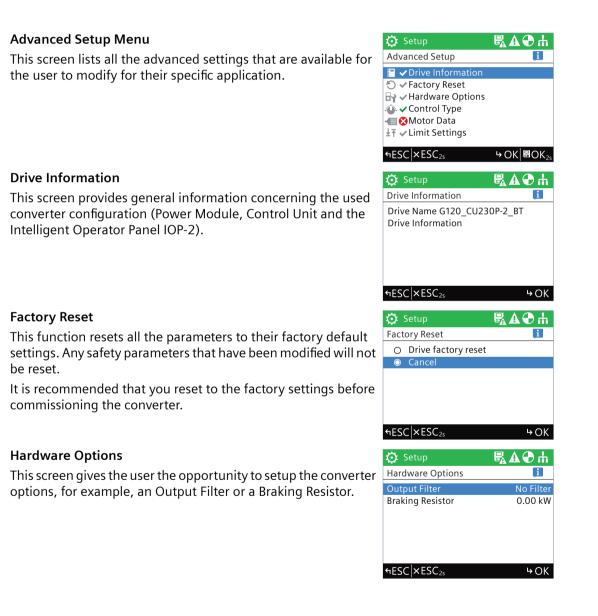
- ✓ The settings for the function at the default settings.
- ✓ The settings for the function have been changed and saved.
- The settings for the function must be checked to ensure the safety settings are correct.

The settings for the function must be checked and corrected if necessary.

This icon indicates that information is available on the selected function by pressing the INFO key.

# **Advanced Setup**

The Advanced Setup process is outlined below and it should be remembered that the screenshots are for example purposes only and may vary from your own IOP-2 display, depending on the firmware version and the actual converter that is being commissioned.



6.1 Example Setups

Type i ndard Drive Control hamic Drive Control pert ESC <sub>25</sub> ♀ Ok p ♣ ♠ ♥ ♣ ata i IEC (50 HZ, SU Induc 400 V 5.90 Arm 2.20 kV 1425.00 rpn 400 Vrm ESC <sub>25</sub> ♥ Ok p ♣ ♠ ♥ ♣ 1425.00 rpn 400 Vrm ESC <sub>25</sub> ♥ Ok
pert ESC <sub>2s</sub> → Ok p
P BC2s P C C SO HZ, SI Induc 400 V 5.90 Arm 2.20 kV 1425.00 rpm 400 Vrm ESC2s P C C C C C C C C C C
p       Image: Constraint of the second
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ata i I IEC (50 HZ, SI Induc 400 V 5.90 Arm 2.20 kV 1425.00 rpn 400 Vrm ESC <sub>25</sub> VO p ESC <sub>25</sub> I I I I I I I I I I I I I I I I I I I
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400 Vrm ESC <sub>2s</sub> CO p CA C H ttings i oltage 400
P Characteria Contracteria Cont
p <b>Lings</b> i oltage 400
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oltage 400 v
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op (OFF3) 0.00
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own Time 10.00
rrent 8.85 Arm ESC <sub>2s</sub> /Ok
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<ul><li>CDS Select</li><li>2104:0 2nd acknowled</li></ul>
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6.1 Example Setups

#### **Application Setup**

This screen allows the application specific functions to be configured. When "Application Setup" is selected, the user is presented with some default application functions, depending on the type of Control Unit that is being used. A grey tick is displayed beside the functions that have not been configured using the IOP-2 and when a function has been configured using the IOP-2, a green tick is shown beside the function in the list.

	🔅 Setup	₣₽₽₽₩
	Advanced Setup	i
n d	보주 ✓ Limit Settings ☆ ✓ Optimisation [도 ✓ I/O setup 品 ✓ Fieldbus Setup	
	<b>℃</b> ✓ Application Setup	
,		
	HESC XESC <sub>2s</sub>	<b></b> •ОК ВОК₂s

Setup Menu

6.1 Example Setups

# **Control menu**

#### Overview

The Control menu allows the user to change the following settings in real-time:

- Setpoint
- Reverse
- Jog
- Custom Hand mode
- Startup in Hand mode
- Hand/Auto disable
- PID Hand Mode

The control menu is accessed from the menu at the bottom-centre of the Status screen, as shown below.

ठ् <del>र</del> ा Sta	tus			<u></u>
Actua	l speed			0 rpm
-1500				1500
Actua	l speed			0 V
0				1000
ø	÷l÷ I÷i	Ŵ	Ų,	

# 7.1 Setpoint

# Setting the Setpoint

The setpoint value determines the speed at which the motor runs as a percentage of its full range of motion.

7.2 Reverse

To change the setpoint, the following actions should be performed:

र्क्ज Status		ф	🕨 Yw Control	th.	🗤 Control	<u></u> н
		0	Setpoint	0.00%	Setpoint	
Actual speed		0 rpm	Reverse	Off	Actual speed	0 rpm
-1500		1500	Jog	Off		
			Custom Hand Mode	Off	-1500	1500
Actual speed		0 V	Startup in Hand Mode	Off	Actual speed	0 V
		1000	Hand/Auto Disable	Off		
0		1000	PID Hand Mode	On	0	1000
					Setpoint	14.00%
②   特	<b>1</b>				0	200
Select Contro	bl		Select Setpoint		Use Touch-wheel Setpoint	to set the

# Note

#### Setpoint in Hertz (Hz) for SINAMICS CU230P-2

The setpoint screen by default displays the motor speed as a percentage of the total possible speed of the motor.

This behaviour changes for the SINAMICS CU230P-2 and SINAMICS G120X where the default setpoint value is displayed in Hertz (Hz).

# 7.2 Reverse

## **Setting Reverse**

The function of the reverse command is to set the direction of rotation of the motor from its normal forward motion.

To reverse the direction of the motor, the following actions should be performed:

🗢 Status	品 🕨	🖌 Yw Control		Reverse	<u></u> ф
Actual speed	0 rpm	Setpoint Reverse	0.00% Off	Off	
-1500 Actual speed	1500 0 V 1000	Jog Custom Hand Mode Startup in Hand Mode Hand/Auto Disable PID Hand Mode	Off Off Off Off On	O On	
Select Control		Select Reverse		Select Off or On	

# 7.3 Jog

# **Setting Jog**

The Jog function, when selected will allow the motor to be manually rotated by a predetermined value with each press of . If s pressed continuously, the motor will rotate continuously until is released.

To enable or disable the Jog function, the following actions should be performed:

😎 Status	н I	🔪 Control	₩ 🕨	por por
Actual speed	0 rpm	Setpoint Reverse	0.00% Off	Off
-1500 Actual speed 0	1500 <b>0 V</b> 1000	Jog Custom Hand Mode Startup in Hand Mode Hand/Auto Disable PID Hand Mode	Off Off Off Off On	O Jog 1 O Jog 2
Select Control		Select Jog		Select Off or On

#### Note

# Selection of Jog frequencies / rpm

It is important that the Jog parameters P1058 and P1059 are set to the required frequencies / rpm for the users application.

# 7.4 Custom Hand mode

## Overview

The custom hand mode allows the user to setup a command source and setpoint source directly from the Intelligent Operator Panel 2 (IOP-2).

When the custom hand mode has been set, the IOP-2 Sensor Control Field can be used as the setpoint source.

The Auto mode is unaffected by any changes made by the custom hand mode function.

A breakdown of all the interconnection inputs is given in the table below.

An example of setting up the custom hand mode is given in the instructions below.

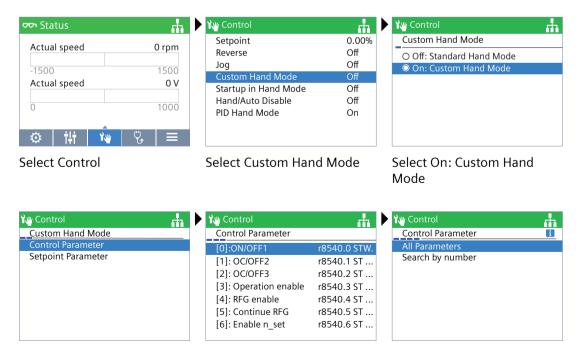
Standard	Standard interconnection				
r8540	STW 1 from IOP-2	Binector Inputs (BI)	p8542	Effective STW1 in Custom Hand mode	
BitO	ON/OFF key	->	Bit0	ON/OFF1	
Bit1	Two quick press of the OFF key	->	Bit1	OFF2	

#### Control menu

7.4 Custom Hand mode

Standar	d interconnection			
r8540	STW 1 from IOP-2	Binector Inputs (BI)	p8542	Effective STW1 in Custom Hand mode
Bit2	A long press of the OFF key	->	Bit2	OFF3
Bit3	Reserved	->	Bit3	Inhibit/enable operation
Bit4	Reserved	->	Bit4	Ramp-function generator enable
Bit5	Reserved	->	Bit5	Continue ramp-function generator
Bit6	Reserved	->	Bit6	Setpoint enable
Bit7	Alarms menu acknowledge all faults	->	Bit7	Acknowledge faults
Bit8	Jog 1 (Control menu)	->	Bit8	Jog 1
Bit9	Jog 2 (Control menu)	->	Bit9	Jog 2
Bit10	Reserved	->	Bit10	Control by PLC
Bit11	Change direction (Control menu)	->	Bit11	Direction of rotating - reversed
Bit12	Reserved	->	Bit12	Speed control enable
Bit13	Reserved	->	Bit13	Motorized potentiometer, setpoint, increase
Bit14	Reserved	->	Bit14	Motorized potentiometer, setpoint, decrease
Bit15	Reserved	->	Bit15	CDS selection
Standar	d interconnection			
r8541	Speed setpoint from IOP-2	Connector Inputs (CI)	p8543	Effective speed setpoint in Custom Hand mode
	N_soll OP	->		Speed setpoint

# Setting up Custom Hand mode example



7.4 Custom Hand mode

Select Control Parameter	Press OK to search for param- eter	Select All parameters
Control	Yw Control 	K₩ Control
<ul> <li>r8540.0: STW1 IOP</li> <li>r9401: Mem_card rem stat</li> <li>r11049: Ftec0 stat_word</li> <li>r11149: Ftec1 stat_word</li> <li>r11249: Ftec2 stat_word</li> <li>r29529: Mpc ZSW</li> <li>p29542: Mpc ser_interl</li> <li>r29545: Mpc bypass comd</li> <li>r29582: Ramp stat</li> </ul>	O: ON/OFF1      1: OC/OFF2     2: OC/OFF3     3: Reserved     4: Reserved     5: Reserved     6: Reserved     7: Acknowledge fault     8: jog bit 0	[0]:ON/OFF1         r8540.0 STW           [1]: OC/OFF2         r8540.1 ST           [2]: OC/OFF3         r8540.2 ST           [3]: Operation enable         r8540.3 ST           [4]: RFG enable         r8540.4 ST           [5]: Continue RFG         r8540.5 ST           [6]: Enable n_set         r8540.6 ST
Select the required control parameter	Select the required digital in- put	Select another control parameter or press ESC to return to the control parameter screen
Control Control Control Control Parameter Setpoint Parameter	Setpoint Parameter	Control       Search by number       Enter the required parameter number and press OK       00752
Select Setpoint Parameter	Select search by number	Enter the required paramete number and press OK
Yw Control       i         Setpoint Parameter       i         Image: image of the state of the sta	Yw Control       Image: Control in the second	Control Custom Hand Mode Control Parameter Setpoint Parameter
	Select the required setpoint	Press ESC to finish editing and

In this example, the converter is now setup to receive the ON/OFF1 command from p8540[0] and the speed setpoint from Analog Input 0 (AI0), from the controlling PLC.

7.5 Startup in Hand mode

# 7.5 Startup in Hand mode

## Overview

Startup in Hand mode allows the converter, under the control of the Intelligent Operator Panel (IOP-2), to startup in Hand mode automatically. The command source is then taken from the off and on buttons of the IOP-2.

An example of setting up the Startup in Hand mode is given in the instructions below.

# Startup in Hand mode example

ण्ज Status	ц	Yw Control	<u></u> ф	Vw Control
Actual speed -1500 Actual speed 0	0 rpm 1500 0 V 1000	Setpoint Reverse Jog Custom Hand Mode Startup in Hand Mode Hand/Auto Disable PID Hand Mode	0.00% Off Off Off Off Off On	Startup in Hand Mode O Off: Startup in Auto Mode On: Startup in Hand Mode
Select Control		Select Startup in Har	nd Mode	Select On: Startup in Hand Mode
Y Control Powerup Setpoint	50 Hz Ŧ 10.00 0.0 Hz Ł	Setpoint Reverse Jog Custom Hand Mode Startup in Hand Mode Hand/Auto Disable PID Hand Mode	0.00% Off Off Off Off Off Off	

The IOP-2 will automatically return to the Control menu and show that "**Startup in Hand Mode**" is "**On**". "Hand/Auto Disable" is greyed out as it cannot be enabled when "Startup in Hand Mode" has been configured.

The converter, after a power-cycle will automatically startup in Hand mode, but the attached motor will not run until the run command is given by the buttons on the IOP-2.

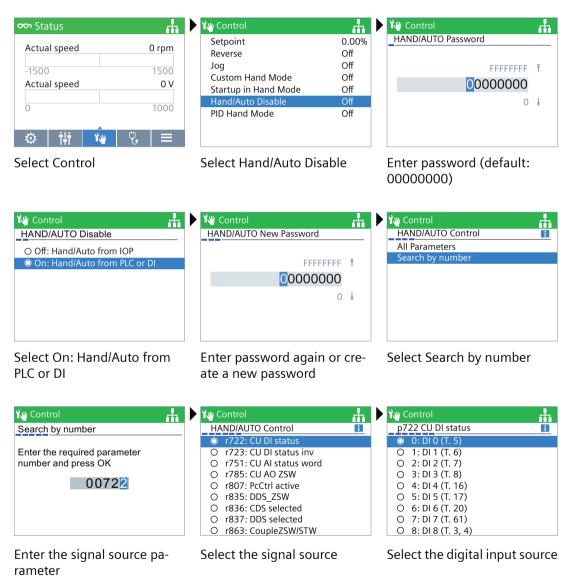
# 7.6 HAND/AUTO disable

#### Overview

The HAND/AUTO disable function disables the HAND/AUTO key on the Intelligent Operator Panel (IOP-2) and pressing the key will not produce any action by the IOP-2.

An example of setting up the Hand/Auto disable mode is given in the instructions below.

# Setting up the HAND/AUTO disable function



# 7.7 PID Hand Mode

ရို္ယ္ Control	ф
Setpoint	0.00%
Reverse	Off
Jog	Off
Custom Hand Mode	Off
Startup in Hand Mode	Off
Hand/Auto Disable	On
PID Hand Mode	Off

Hand/Auto is now enabled. Startup in Hand Mode cannot be selected

The HAND/AUTO button is now disabled and local control of the IOP-2 cannot be activated by the HAND/AUTO button. In this example, the converter is now setup to receive the HAND/ AUTO command from Digital Input 0 (DI0).

#### Note

#### Power-cycle required to complete the HAND/AUTO disable function

When the HAND/AUTO disable function is initiated the function will not become active until a power-cycle of the IOP-2 has been performed. When the HAND/AUTO disable function is turned off, again, a power-cycle of the IOP-2 is required to complete the deactivation of the function.

# 7.7 PID Hand Mode

#### Overview

# NOTICE

#### PID Hand Mode is only available for the SINAMICS G120X range of products

Currently PID Hand Mode is only available for the SINAMICS G120X (firmware version 1.04 or later) range of products. If you are not using an SINAMICS G120X product, the PID Hand Mode will not be visible on your IOP-2.

The PID Hand Mode of the IOP-2 allows the setting up of a precise process control utilizing the PID controller within the Converter that is driving a motor. The PID loop is used to maintain a process variable, such as the speed setpoint. The desired setpoint speed can be set using the IOP-2 PID Hand Mode function as shown in the example procedure.

# Setting up the PID Hand Mode example

ठ्ठ Status	<u>ф</u>
Actual speed	0 rpm
-1500 Actual speed	1500 0 V
0	1000
© 👬 💘	୍ ଓ   ≡

# Select Control Menu

ໃ∰ Control	<b></b>
PID Hand Mode	
○ Off: PID Hand Mode	
On: PID Hand Mode	

# Select On: PID Hand Mode

វៃឃ្មូ Control	<u>њ</u>
PID Setpoint	
Actual speed	0 rpm
-1500	1500
Actual speed	0 V
0	1000
Setpoint	14.00%
0	200

#### Set the required PID Setpoint



Select On: Startup in PID Hand Mode

Yw Control	<u>н</u>
Setpoint	0.00%
Reverse	Off
pol	Off
Custom Hand Mode	Off
Startup in Hand Mode	Off
Hand/Auto Disable	Off
PID Hand Mode	Off

#### Select PID Hand Mode

ነት Control	<u>ф</u>
PID Setpoint	0.00%
Reverse	Off
Jog	Off
Custom Hand Mode	Off
Startup in PID Hand Mode	Off
Hand/Auto Disable	Off
PID Hand Mode	On

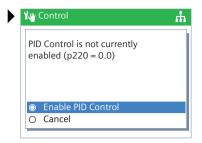
# IOP-2 returns to Control Menu

$\mathbf{H}$
.00%
f
f
f
f
f
ı

IOP-2 returns to Control Menu

🏰 Control	
Powerup PID Setpoint	
	200 % ₹
	014.00
	0.0 % ±

Set the required Powerup PID Setpoint



#### Select Enable PID Control

🏰 Control	
PID Setpoint	0.00%
Reverse	Off
pol	Off
Custom Hand Mode	Off
Startup in PID Hand Mode	Off
Hand/Auto Disable	Off
PID Hand Mode	On

# Select PID Setpoint

វៃរុរូ Control	ф
PID Setpoint	14.00%
Reverse	Off
log	Off
Custom Hand Mode	Off
Startup in PID Hand Mode	Off
Hand/Auto Disable	Off
PID Hand Mode	On

#### Select Startup in PID Hand Mode

🏰 Control	
PID Setpoint	14.00%
Reverse	Off
Jog	Off
Custom Hand Mode	Off
Startup in PID Hand Mode	On
Hand/Auto Disable	Off
PID Hand Mode	On

#### IOP-2 returns to Control Menu

#### Control menu

# 7.7 PID Hand Mode

የም Control	ф
PID Setpoint	14.00%
Reverse	Off
pol	Off
Custom Hand Mode	Off
Startup in PID Hand Mode	On
Hand/Auto Disable	Off
PID Hand Mode	On
Save PID Hand Setpoint	

Yw Control         Image: Control           Save PID Hand Setpoint         Image: Control
Continue
Cancel

🇤 Control	<u></u> ф
PID Setpoint	14.00%
Reverse	Off
log	Off
Custom Hand Mode	Off
Startup in Hand Mode	On
Hand/Auto Disable	Off
PID Hand Mode	On
Save PID Hand Setpoint	

Select save PID Hand Setpoint<sup>1</sup>

Select Continue

IOP-2 returns to the Control Menu

To cancel all PID Hand Mode functions, select PID Hand Mode and turn the function OFF. This will cancel all PID Setpoint functions, including Startup in PID Hand Mode.

<sup>1</sup>"Save PID Hand Setpoint" – This saves the current PID hand setpoint as the Startup in PID Hand setpoint. For example, if the customer has already set a Startup in PID Hand setpoint and has started up their drive and tweaked the setpoint from the PID setpoint screen, this option would save the tweaked value as the new Startup in PID Hand setpoint.

# Menu

# 8.1 Menu overview

### Overview

# MARNING

#### Protection of project data files from unauthorized usage

Transportation of project data files have to be secured by technical means, for example, encrypted/signed emails, encrypted/signed USB-sticks etc., especially in the public internet.

Project data files have to be stored with restricted access within the OEM/end customer area, for example, access restrictions to SharePoints, databases, etc. by user management with, for example, the use of credentials.

The "Menu" is selected from the five menu options at the bottom of the IOP-2 screen.

When the "Menu" option is selected the following functions are displayed:

- Setup
- Parameters
- Diagnostic
- Up/Download
- Support
- Extras

By sliding your finger around the Sensor Control Field or using the arrow keys, the required function can be highlighted. Pushing the OK confirms the selection and further sub-menus will be displayed. Pressing ESC once will return the IOP-2 to the previous screen, a longer press will return the display to the "Status" screen.

For information on the IOP-2 compatibility, see 🔛 Introduction (Page 11).

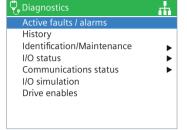
8.2 Diagnostics

# 8.2 Diagnostics

# **Diagnostics menu**

When the diagnostic function is selected the following options are presented:

- Active faults/alarms
- History
- Identification/Maintenance
- I/O status
- Communications status
- I/O simulation
- Drive enables



# Active faults/alarms

When this option is selected the screen will display any active faults and alarms that have not yet been acknowledged.

Each fault and alarm can be selected and by pressing the INFO key or the OK key, an explanation of the fault or alarm will be displayed.

Diagnostics Active faults/alarms		
		Acknowledge all
	1601 1611 1600 52 60 503	Defect in cross com Passivated STO wit Power stack SW fault Asic Timeout UnderVoltage Limit

# History

When this option is selected the screen will display a list of all previous faults and alarms with the time that they occurred. Each fault and alarm can be selected and by pressing the INFO key or the OK key, an explanation of the fault or alarm will be displayed.

🖁 Diagno:	stics 🔥 🛣
History	i
<b>X</b> 73	Control Panel setpoi 11/07/2017 12:04:
<ul> <li>№ 1601</li> <li>№ 1611</li> <li>№ 1600</li> <li>№ 52</li> <li>№ 60</li> <li>▲ 503</li> </ul>	System startup error Defect in cross com Passivated STO wit Power stack SW fault Asic Timeout UnderVoltage Limit

# Identification/Maintenance

Displays specific technical information regarding the Control Unit and Power Module to which the IOP-2 is attached will be displayed. The actual information displayed depends on the type of Control Unit and Power Module to which the IOP-2 is connected.

🖁 Diagnostics	<sub>t</sub>
Indentification/maintenance	
MANUFACTURER ID: 0042	
ORDER ID: 6SL3244-0BB00-1BA0	_
SERIAL NUM: XAX917-001575	
HARDWARE REV: 00102	
SOFTWARE REV: V043021	
REVISION COUNT: 0000	
PROFILE ID: 3A00	_
	_
X ESC 1/2►	

# I/O status

This option displays a list of the digital and analog inputs and outputs of the converter and their current status.

This is an information screen and cannot be changed.

Pressing ESC will return the display to the previous menu. In the example shown opposite, the status of the digital inputs are displayed.

ł	🖁 Diag	gnostic		- +
	I/O 5	Status		
	Sta	tus digi	tal inputs	
	Sta	tus digi	tal outputs	
	Sta	tus ana	log inputs	
	Sta	tus ana	log outputs	
ts				
	🖁 Diag	gnostic	S	-
	Stat	tus digi	tal inputs	
	DI#	Status	Function/BICO	
	0		1: ON/OFF1	
	1		12: Dir reversal	

15: n\_fixed\_setp Bi..

0: No pre-assignmen..

3 4 8.2 Diagnostics

# **Communications status**

This option displays the status of the fieldbus interface and the details of the settings for the data exchange, for example status words and control word lengths.

In the example shown opposite, the status of the fieldbus communications is shown.



Diagnostics	⊕₼
Fieldbus interface	
PN	
PN Name Stat act	
g120	
PN IP addr act	
0.0.0.0	
PN Subnet Mask act	
0.0.0.0	
PN MAC addr	
00:1c:06:45:61:a4	

# I/O simulation

# WARNING Loss of control of the converter If the converter is started using the I/O simulation and the IOP-2 is removed from the converter it will not be possible to stop the converter running the motor. If the I/O simulation is activated, then only the I/O simulation can be used to stop the converter. The simulation is performed in the converter itself and is also retained when the connection with the IOP-2 is interrupted. Therefore, there must be an emergency stop circuit in the

• Parameter connections for the Analog Outputs and Digital Outputs will be overwritten by the I/O simulation. These parameters should be checked to ensure they have been reinstated after leaving the I/O simulation.

hardware. The appropriate measures must be taken by the user.

The IOP-2 simulation screen allows digital and analog I/Os to be simulated without the requirement for external signals. These features are of great benefit during commissioning and fault finding, as the user can quickly simulate a situation without using wires, tools and external equipment.

For example:

- A digital input can be made high without any wires in the terminals.
- An analog input or output can be driven to any value without any wires in the terminals.
- A simulation can be overridden and made high.

The screen presents the following options:

- I/O all I/Os can be simulated individually.
- Status this indicates the real-time status of the input or output.
- Setpoint this column displays the editable value that will be simulated.
- Activate this column will activate / deactivate the simulation for the corresponding I/O.

#### **Drive enables**

The drive enables screen displays a list of all the current enabling signals for the converter. If the enable signal is present and active it will be selected  $\blacksquare$ . If the enable signal is not present and is not active it will be unselected  $\Box$ .

This screen is read-only and is for information purposes only.

🖁 Dia	gnostics		<u></u> н
I/O Sin	nulation		
10	Status	Setpoint	Activate
DI 0 DI 1 DI 2 DI 3 DI 4 DI 5 DI 6	0 0 0 0 0 0 0	0 0 0 0 0 0 0	
₩ESC			∕ОК

Drive enables
□ 0: ON/OFF1
□ 1: OC / OFF2
2: OC / OFF3
3: Operation enable
□ 4: RFG enable
5: Continue RFG
6: n_set enable

8.3 Parameters

# 8.3 Parameters

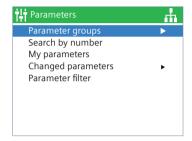
## Parameter menu

For information on IOP-2 compatibility, see

The parameter menu allows the user extensive functionality and access to all the converter parameters. When this option is selected the user is given the opportunity to perform parameter orientated functions grouped in the following manner:

- Parameter groups
- Search by number
- My parameters
- Changed parameters
- Parameter filter

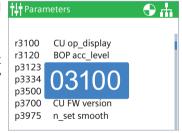
👓 Status				
Actual speed				0 rpm
-1500				1500
Actual speed				0 V
0				1000
◎ 前	¥4	Y	Ų,	



# Fast scroll

When searching through any large parameter list, the Fast scroll function will automatically start when the user slides their finger around the Sensor Control Field in a fast motion.

A large blue box will appear on the screen, showing the current parameter number, with each scroll the number will increase by 1000. When the user stops scrolling, the parameter number nearest to the number displayed will be selected.



# Parameter groups

#### All parameters

This option allows the user access to the individual parameters of the converter. The default filter is "Standard" which allows the user access to the most frequently used parameters.

#### Commissioning

This screen displays a complete listing of all the parameters required for quick commissioning. The parameters are listed in numerical order and can be accessed to either confirm the set values or modified should there be a need to fine tune the application or correct any errors in the parameter values.

#### Commissioning interface

Allows the communications settings to be configured for the commissioning interface.

#### Saving & reset

This option allows the user access to all the parameters regarding the saving and reset functions of the converter. Each parameter displays it's currently set value and these can be modified if required.

#### System information

This screen displays all the parameters that contain system information regarding the converter. The majority of these parameters are read-only and are for information purposes only.

#### Basic settings

Displays the effective Drive Data Set (DDS). Each basic setting can be selected and modified if necessary.

#### Inputs/outputs

This option allows access to all the available parameters to configure the digital and analog I/Os.

The user can navigate through the various inputs and outputs to see the current configuration of the inputs and outputs and, if necessary access the parameters directly to modify their values.

#### Setpoint channels

This option allows the user to display and modify the setpoint parameters.

#### Operating mode

This option allows the user to display and modify the operating mode parameters.

#### Drive functions

This option allows the user direct access to the parameters regarding the drive functions.

It is important that if any parameters concerning the above mentioned functions are to be modified, that the converter/motor system is in a safe state prior to the parameter changes.

#### Communications

This option allows the user direct access to the parameters that control and configure the communications fieldbus of the converter. The parameters can be viewed to confirm their settings and values, they can also be modified if they are not read-only parameters.

#### Diagnostics

This option allows the user direct access to the parameters that monitor the state of the system.

All the parameters under these groupings are read-only and cannot be modified.

8.3 Parameters

# Search by number

This option allows the user to search for a specific parameter number.

If the parameter number does not exist, the screen will display a choice between "Select a new number" or "Go to the nearest parameter number".

Parameters	$\mathbf{H}$
Search by number	
To enter a parameter number turn the wheel and press OK	
0000	

# My parameters

This option allows the user to select the parameters that they wish to list. The user is presented with a list of parameters that can be selected. Once selected - only those parameters are displayed when the "My Parameters" option is selected. There are additional options that allow the user to manage their list of parameters.

# Copying the "My Parameters" list to another IOP-2

When a "My Parameters" list is created, it saves the lists in the **config.bin** file on the IOP-2.

To copy the config.bin, the following procedure should be performed:

- 1. Connect the IOP-2 via the USB to your PC (the IOP-2 will enter "Mass Storage" mode.
- 2. Navigate to the config folder (shown in the screenshot).
- 3. Copy the config.bin file to a suitable location on your PC.
- 4. Disconnect the IOP-2 and connect a new IOP-2 and copy the **config.bin** file to the new IOP-2.

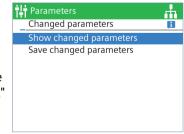


When the "Changed parameters" option is selected the IOP-2 will search the converter parameter list for all the parameters that have had their values changed from the factory default settings.

The list of changed parameters can either be displayed on the IOP-2 screen or it can be saved to a ".CSV" file in the "\user\cps\" folder on the IOP-2.







## **Parameter filter**

This option allows the user to select the parameter access level. Standard is the default access level, which gives the user access to the most frequently used parameters. Expert level gives access to all available parameters.

ili Pa	rameters	ф.
Para	meter filter	
0	Standard	
0	Expert	

# 8.4 Protecting the converter settings

#### Overview

Once the converter has been fully commissioned for the required application, it is possible to protect the final settings with one of the three different protection modes:

- Know-how protection Allows the settings of the converter to be protected against unauthorized viewing or changes. It can be configured in a number of different ways, which will be explained in the relevant section in this chapter.
- Absolute Know-protection Allows the settings of the converter to be permanently protected against unauthorized viewing or changes. Once configured you can only gain access to the settings by performing a drive factory reset; causing all settings to be returned to their factory default setting.
- Write protection Prevents accidental changes to the settings of the converter.

#### Know-how protection

# A CAUTION

#### Know-how protection should be enabled last

Before enabling the Know-how protection function, all commissioning and configuration of the converter must first be completed. If Know-how protection is enabled prior to the completion of all the necessary commissioning and configuration steps, it may prohibit the completion of the commissioning and configuration process.

Know-how protection is designed to prevent unauthorized viewing or changes to the parameter settings of the converter. It can also be configured to allow or prohibit the copying of the parameters from one converter to another converter.

There are four different types of protection available in the configuration menu:

- Know-how protection without copy protection You can transfer the converter settings to other converter using a memory card (MMC), If no selection is made in the 'Configure' screen, then 'Know-how protection without copy protection' is the default method that will be implemented.
- Know-how protection with basic copy protection After replacing a converter, to be able to operate the new converter with the settings of the replaced converter without knowing the password, the memory card must be inserted in the new converter.
- Know-how protection with extended copy protection It is not possible to insert and use the memory card in another converter without knowing the password.
- **Permit trace** Allows the diagnostic trace and measurement functions to be performed on the converter. This option will only appear if your converter has trace function capability.

When know-how protection is active the following protections are provided:

- The values and setting of parameters are invisible.
- Read-only (r) parameters remain visible.
- In addition, you can define an exception list which will allow parameters to be viewed or changed by the user.
- Adjustable parameters cannot be changed using any of the commissioning tools
- Locked functions:
  - Automatic controller optimization
  - Stationary or rotating measurement of the motor data identification
  - Deleting the alarm history and the fault history
  - Generating acceptance documents for safety functions
- Executable functions:
  - Restoring factory settings
  - Acknowledge faults
  - Displaying faults, alarms, fault history and alarm history
  - Reading out the diagnostic buffer

When know-how protection is active, support can only be provided (from Technical Support) after prior agreement from the machine manufacturer (OEM).

# A CAUTION

#### Copy protection will not work without the correct memory card

If the copy protection functions are selected/enabled and the correct type of memory card is not inserted into the converter, the copy protection function will fail.

To use copy protection the following memory card must be used: **Siemens MMC card, order** number: 6SL3054-4AG00-2AA0

#### Example of enabling Know-how protection

Parameters	∂₩⟩	🕌 Parameters 🔒 🗛 🕀 🚠	Parameters	€
Parameter groups	•	A Warning backup password	Know-how protection	
Search by number			Configure	•
My parameters		Know-how protection prevents	Activate	►
Changed parameters	•	unauthorized reading of the inverter settings. Once activated there is no way	Exception list	•
Parameter filter		to unlock the inverter without the	Edit password	►
Know-how protection	•	password!	Absolute know-how	•
Write protection	•			
		× ESC ✓ OK		
Select 'Know-how protection'		Password warning is dis-	Select 'Configure'	

played. Press OK to contin-

ue

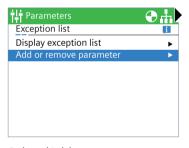


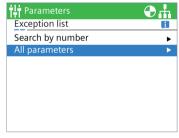
Parameters	<b>0</b> #	<b>1</b> Parameters
Know-how protection		Exception list
Configure	•	Display exception list
Activate	•	Add or remove parameter
Exception list	•	
Edit password	►	
Absolute know-how	•	
elect 'Exception list'		Select 'Display exce

Select the required functions. Press OK to continue

Select 'Display exception list'

Parameters	Э <b>н</b>	
Exception list	<u>F</u>	
Empty		
Linpty		





Parameters contained in the exception list are displayed. Press ESC

Select 'Add or remove parameter'

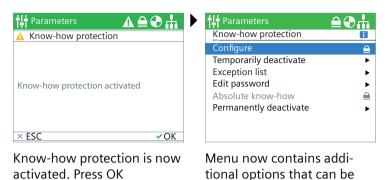
Select 'All parameters'

Parameters Parameters Эщ Parameters ᠿ᠊᠋᠊ᡣ Add or remove parameters i Know-how protection i Enter new password P40 Reset energy consumption Configure ► 1 2 3 4 5 6 7 8 9 0 🛥 + P43 Enable energy usage ► Activat + P45 Display values smoothing .... Exception list ► abcefghij + P96 Application class Edit password ► + P133 Motor configuration k l m n o p q r s t Absolute know-how • Encoder 1 encoder data .... + P187 uvwxyz.-ABC + P188 Encoder 2 encoder data .... + P201 Power Unit code number + P205 Power unit application ←ESC ×ESC<sub>2s</sub> ✓OK til til OK<sub>2s</sub> Select 'Activate' Select required parameters Enter a new password and and add or delete by pressing then confirm password

OK

Эm

┙



selected.

#### Temporarily deactivate and Permanently deactivate Know-how protection

Once Know-how protection has been activated two additional options appear in the menu, these are:

- Temporarily deactivate This allows the Know-how protection to be deactivated, for example, a parameter change is required. When the converter is restarted, Know-how protection will be fully activated.
- Permanently deactivate This allows the Know-how protection to be deactivated as if knowhow protection was never active.

If you select 'Temporarily deactivate' the password must be entered before deactivation can occur. If you then select 'Permanently deactivate' the password is not required. If you only select 'Permanently deactivate' the password is required.

#### **Absolute Know-how protection**

Absolute Know-protection allows the settings of the converter to be permanently protected against unauthorized viewing or changes. Once configured you can only gain access to the setting by performing a drive factory reset; causing all settings to be returned to their factory default setting.

#### Example of enabling Absolute Know-how protection

Harameters       Harameters         Know-how protection       i         Configure       >         Activate       >         Exception list       >         Edit password       >         Absolute know-how       >	A Warning Absolute KHP A Warning absolute KHP After activating absolute KHP, all protected parameters will only be editable after a drive factory reset.	Absolute know-how protection To enable absolute KHP enter 23072021 and press OK. To cancel, press ESC
Select 'Absolute Know-how'	× ESC ✓ OK Absolute KHP warning is	Enter 23072021 to confirm
Select Absolute KIIOW-IIOW	displayed	activation

played. Press OK to continue



firm password

Absolute KHP warning is displayed. Press OK to continue

Parameters <u>●</u>●₼ Know-how protection H Configure Temporrarily deactivate Exception list ► Edit password Absolute know-how Permanently deactivate 

KHP menu is now displayed with the locked functions greyed out.

#### Write protection

Write protection, when enabled, stops all writeable parameters from being changed. All parameters can still be viewed and no password is required to activate or deactivate this function. Write protection can be turned off by selecting 'Disable write protection'.



8.5 Up/Download

# 8.5 Up/Download

#### Overview

The upload and download options allow the user to save parameter sets to the various memory storage that is available to the system.

For further information on saving, copying, cloning and creating custom parameter sets, see Customer parameter sets (Page 71).

#### 🕂 Up / Download

Download: panel to drive Upload: drive to Panel Delete panel parameter set Drive to memory card Memory card to drive Rename parameter set ф.

# 

# Unexpected behavior of converter

During the transfer of data to and from the converter, it is essential that the transfer is not interrupted and the process is allowed to be completed. If the process is interrupted, it is possible that the data could be corrupted and the system may behave in an unexpected manner. Should an interruption of the transfer process occur, then it is highly recommended that a factory reset of the converter is performed prior to any further parameterization or giving the converter control of the application.

# Fault screen during up/download

If during the up/download process a fault occurs and the fault screen is displayed, press ESC if you wish the up/download to be continued. If OK is pressed, it will cancel the up/download process.

#### **Safety Parameters**

If safety parameters are to be downloaded a function test of the safety functions has to be performed. Please refer to the "Safety Integrated Function Manual" which can be found at the hyperlink below:



Safety Integrated Function Manual (<u>http://support.automation.siemens.com/WW/view/en/</u>50736819)

# Using the IOP-2

The IOP-2 must be handled with particular care for all SINAMICS devices that use an IOP-2 so that no malicious software or erroneous parameterizations are spread between different commissioning PCs or inverters.

# \Lambda warning

#### Risk of death due to software manipulation when using exchangeable storage media

Storing files onto exchangeable storage media amounts to an increased risk of infection of the commissioning PCs, e.g. with viruses or malware. Incorrect parameter assignment can cause machines to malfunction, which can lead to injuries or death.

 Protect files stored on exchangeable storage media from malicious software using appropriate protection measures, e.g. virus scanners.

# M WARNING

#### Risk of death due to software manipulation when using exchangeable storage media

Storing the parameterization (incl. Safety Integrated parameterization) on exchangeable storage media carries the risk that the original parameterization (with Safety Integrated) will be overwritten, for example, by the IOP-2 of another drive without Safety Integrated. Incorrect parameter assignment can cause machines to malfunction, which can lead to injuries or death.

- Ensure that only the IOP-2 that belongs to the respective converter is used.
- Ensure that only trained or authorized personnel have access to the enclosures, cabinets or electrical equipment rooms.

#### NOTICE

#### Only changed parameters will be copied

When using the 'Panel to drive' or the 'Drive to panel' functions of the IOP-2, only those parameters that have been changed/modified will be copied. Parameters that are set at their default settings will not be copied.

#### **Command Line Interface (CLI)**

#### Overview

The CLI function allows the user to create a custom parameter listing and download the listing directly to the drive using the IOP-2 download process.

The CLI file can be created using a suitable text editor, for example, the Windows Notepad application. The format of the CLI is as follows:

#### wrp <number> <index> <value>

Where wrp is the command to write a parameter, followed by the parameter number, the parameter index and the parameter value. For example, to write a parameter to the drive to set the Ramp-up time to 5 seconds, the following format would be used:

#### wrp 1120 0 5.0

# 8.5 Up/Download

Each parameter in the listing must be on its own line, with no excess spaces between the individual components of the command line, followed by a return.

Once the file has been created, the file should be stored on the IOP-2 in the "user/cps" folder with the file extension cli, for example, ramp.cli.

The naming of the file follows the normal conventions and is restricted to only the ASCII character set, but it is suggested that the file name should be in lower case with only numbers and letters without spaces, followed by the correct file extension.

#### List of commands

Command	Format	Example	Remarks
Write a parameter	wrp <number> <index> <val- ue&gt;</val- </index></number>	wrp 1120 0 5.0	Set P1120 to 5 seconds
Read a parameter	rdpw <param/> <index> <val- ue&gt; <timeout ms=""></timeout></val- </index>	rdpw 10 0 0 5000	Wait 5 seconds for p10 to go back to 0
Read a BICO parameter	rdpw <param/> <index> <par- am&gt; <index> &lt; timeout ms&gt;</index></par- </index>	rdpw 840 0 722 5 1	Allows 1 ms to confirm the OFF1 signal is set to Digital In- put 5
Write a BICO parameter	wrp <param/> <index> <par- am&gt; <index bit=""></index></par- </index>	wrp 840 0 722 0	Set on/off to Digital Input 0
Write a BICO parameter 1 or 0	wrp <param/> <index> &lt;1/0&gt;</index>	wrp 1070 0 1 1	Set signal source is set 100%
To set parameter index bit high or low	<wrpbit><param/><in- dex&gt;<bit>&lt;0/1&gt;</bit></in- </wrpbit>	wrpbit 108 0 18 1	Activate Free Function Blocks
Comment	rem <text></text>	rem This is a comment line	Only one comment on each line

#### Downloading procedure

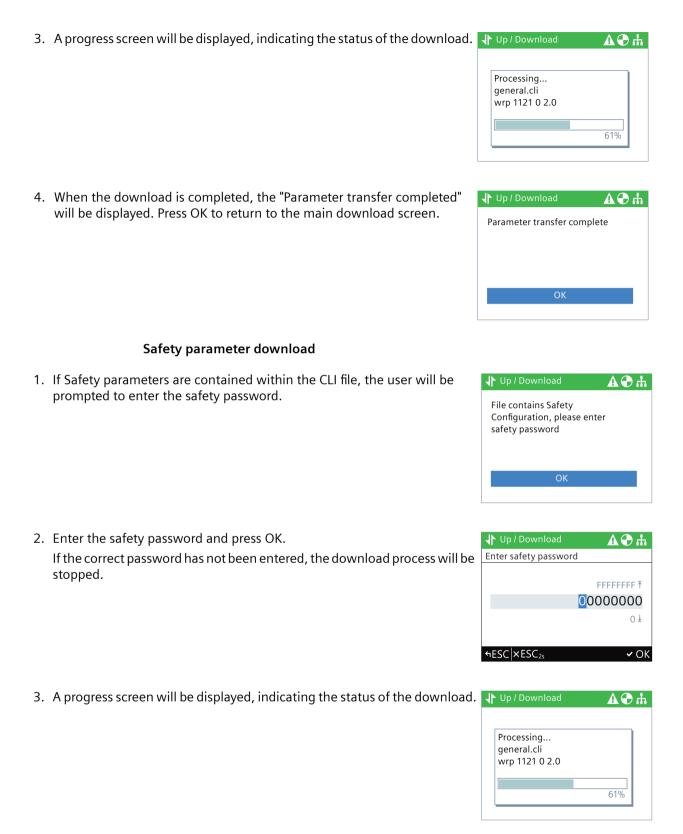
1. Navigate to the Up/Download screen and select "Download: panel to drive".

#### Up / Download

ф Download: panel to drive Upload: drive to Panel Delete panel parameter set Drive to memory card Memory card to drive Rename parameter set

2. Select the CLI file to be downloaded to the drive.





8.5 Up/Download

4. When the download is completed, the "Parameter transfer completed" with be displayed.

Press OK to return to the main download screen.

↓ Up / Download	▲⊕ሐ
Parameter transfer comp	lete
ОК	

#### **Error messages**

# 

#### **Unexpected behavior**

If the download process is canceled for any reason, all parameters that have been overwritten by the download process will remain changed. The drive may be in an unknown state and its behavior may not be as expected. A factory reset should be performed to ensure that the drive is in a known, safe state.

# 1. Incorrect type of argument

The format of the parameter in the file does not conform to the required format.

Press OK will return the IOP-2 to the download screen.

#### Remedy

Edit the CLI file and correct the formatting of the parameter, in this case, delete the "tt" and replace it with the correct parameter number then restart the download process.

#### 2. Parameter not written

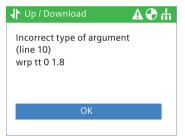
The parameter could not be written to the drive because the parameter was not set to the correct value or range of the index.

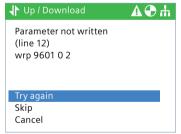
The user has three options:

**Try again:** The IOP-2 will attempt to write the parameter to the drive again, but if it is a restricted parameter it will fail again. If successfully written, the download process will continue until it has completed.

**Skip:** Ignore the parameter and do not attempt to write it to the drive. The download will continue until it is completed.

**Cancel:** The download process will be canceled and the IOP-2 will return to the normal download screen.





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expected

 The download of the parameters to the drive was not completed successfully.
 Press OK to return to the normal download screen.
 CLI file processing incomplete drive behaviour may not be as

# 8.6 Support

#### Overview

()

The Support function on the IOP-2 allows the user to access Siemens Customer Support assistance and information in a number of ways depending upon the individual requirements.

#### **Industry Online Support**

The Online Support option gives the user the ability to gather technical information about the connected whole system, or an individual component of the system, such as Order number, Serial number, firmware version, active alarms.

When the generated 2D matrix code is scanned (in the example below, using the Siemens app) the user is presented with all the available technical information for their device, for example, Serial numbers, Version numbers, FAQs, Manuals, Certificates, Product Notes, Downloads and Application examples, plus the ability to initiate a Technical Support request.

#### **Local Siemens Partner Support**

This option takes the user to the Siemens online Industrial automation help site.

After completing some very simple dropdown menu selections, the contact details of the Local Siemens Partner for your region is displayed.

#### **Download the Siemens App**

You can download the necessary Siemens app using the menu item "Download the Siemens App" which will take you to the appropriate Siemens site that will direct the user to the correct site for either Android or iPhone Smartphone platforms.

The Siemens mobile app site is given at the link below:

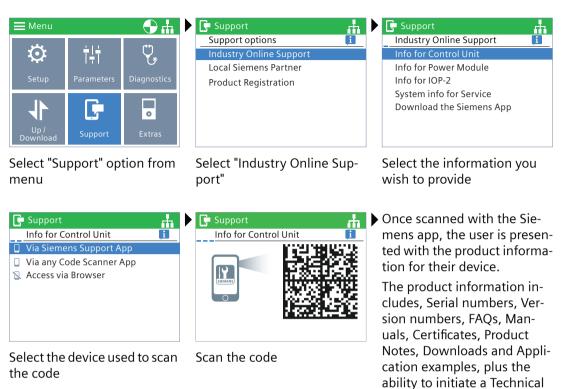
Siemens mobile app (https://support.industry.siemens.com/cs/ww/en/sc/2067)

#### Industry Online Support example

#### Menu

8.6 Support

#### A brief example of the various options is shown below:



#### Local Siemens Partner example



menu ner"

Select "Local Siemens Part-

Scan the QR code

Support request.

When the QR code is scanned, the user is taken to the Siemens Industrial support site. After selecting the correct country, region, the user is given the contact details of their Local Service Partner.

## **Product Registration example**







Select "Support" option from menu

Select "Product Registration" Scan th

Scan the QR code

When the QR code is scanned, the user is taken to the Siemens Industrial support site, where the registration information for your product can be entered and submitted to complete the registration process.

# 8.7 Customer parameter sets

### Overview

Custom parameter sets can now be created and stored on the Intelligent Operator Panel (IOP-2). The IOP-2 can store up to 255 parameter sets with customized names. 8.7 Customer parameter sets

The steps to create and store a custom parameter set on the IOP-2 is given in the procedure outlined below.

#### Note

#### Custom parameter set filename limitations

Although the filename for a custom parameter set can be up to 96 characters in length, if all the filenames are 96 characters long, it will eventually limit the number of parameter sets that can be saved on the IOP-2.

This is due to the specialized nature of the IOP-2's internal memory system.

#### Standard parameter set access

New standard parameter sets can be uploaded from the drive to the IOP-2, these files will be stored in the "user/cps" folder on the IOP-2.

#### Parameter set naming convention

The IOP-2 automatically names the uploaded parameter sets using the following naming convention:

yymmdd-hhmm-PS???, where ??? is the sequential parameter set number.

When the IOP-2 is connected to a Control Unit with a Real-Time Clock (RTC), it will display the parameter set filename with the current time and date stored on the IOP-2, for example, 180125-1126-PS001.

When the IOP-2 is connected to a Control Unit without a RTC, it will display the parameter set filename as yymmdd-hhmm-PS001, so only the parameter set number will be changed.

#### Deletion of characters or filename

When editing the filename with the on-screen keyboard the following actions should be noted:

- When the name is displayed, typing any character will append the character to the filename automatically.
- When the filename is first displayed, the whole filename can be deleted by a two second press of the OK button.
- If individual characters need to be deleted, then use the on-screen keyboard backspace icon.

### Using the IOP-2

The IOP-2 must be handled with particular care for all SINAMICS devices that use an IOP-2 so that no malicious software or erroneous parameterizations are spread between different commissioning PCs or inverters.

## 🔨 warning

#### Risk of death due to software manipulation when using exchangeable storage media

Storing files onto exchangeable storage media amounts to an increased risk of infection of the commissioning PCs, e.g. with viruses or malware. Incorrect parameter assignment can cause machines to malfunction, which can lead to injuries or death.

• Protect files stored on exchangeable storage media from malicious software using appropriate protection measures, e.g. virus scanners.

# \Lambda warning

### Risk of death due to software manipulation when using exchangeable storage media

Storing the parameterization (incl. Safety Integrated parameterization) on exchangeable storage media carries the risk that the original parameterization (with Safety Integrated) will be overwritten, for example, by the IOP-2 of another drive without Safety Integrated. Incorrect parameter assignment can cause machines to malfunction, which can lead to injuries or death.

- Ensure that only the IOP-2 that belongs to the respective converter is used.
- Ensure that only trained or authorized personnel have access to the enclosures, cabinets or electrical equipment rooms.

## Creating a custom parameter set

This procedure makes the following assumptions:

- The user is conversant with the copying and renaming of files in the Windows environment
- The user is conversant with commissioning the converter
- The user has already changed all the relevant parameters for their application

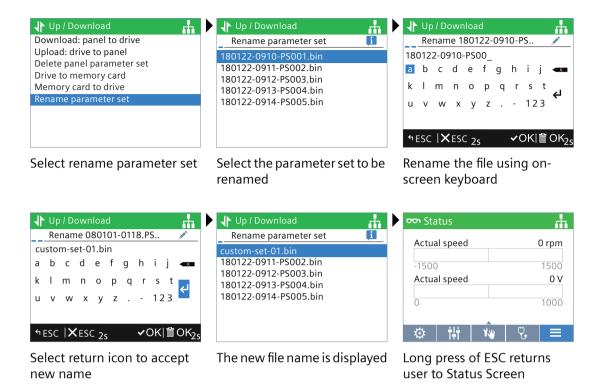
Status	<u>н</u>	🗎 Menu		<b>⊕</b> #	Up / Download
Actual speed	0 rpm	$\odot$	<u>†</u> ‡‡	Ų,	Upload: drive to panel
1500 Actual speed	1500 0 V	Setup	Parameters	Diagnostics	Available Parameter Sets = 255
0	1000	1	C,	•	Press OK to create new parameter set.
🌣   <del>† †</del>   🙀	\$ ■	Up / Download	Support	Extras	
elect Menu		Select Up	/Downloa	d	Select Upload: Drive to



The number of available parameter sets are displayed The drive parameter settings are uploaded

The filename of the parameter set is displayed

#### 8.7 Customer parameter sets



## Copying IOP-2 parameter sets and configuration data

#### WARNING

#### Risk of death due to software manipulation when using exchangeable storage media

Storing files onto exchangeable storage media amounts to an increased risk of infection of the commissioning PCs, e.g. with viruses or malware. Incorrect parameter assignment can cause machines to malfunction, which can lead to injuries or death.

• Protect files stored on exchangeable storage media from malicious software using appropriate protection measures, e.g. virus scanners.

# M WARNING

#### Risk of death due to software manipulation when using exchangeable storage media

Storing the parameterization (incl. Safety Integrated parameterization) on exchangeable storage media carries the risk that the original parameterization (with Safety Integrated) will be overwritten, for example, by the IOP-2 of another drive without Safety Integrated. Incorrect parameter assignment can cause machines to malfunction, which can lead to injuries or death.

- Ensure that only the IOP-2 that belongs to the respective converter is used.
- Ensure that only trained or authorized personnel have access to the enclosures, cabinets or electrical equipment rooms.

The IOP-2 file structure has been designed to allow the easy copying of parameter sets and other configuration data from one IOP-2 to another by using the Windows File Explorer function.

This is accomplished by simply copying the "user" folder from the IOP-2 to any number of other IOP-2 operator panels. The IOP-2 file structure is shown below.

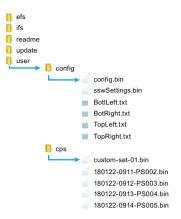


Figure 8-1 File structure of the IOP2

The "config" folder contains all the settings that have been changed on the IOP-2 itself, for example, the language settings, lighting duration and the date/time settings, etc.

The "cps" folder contains all the downloaded or customised parameters sets and the text files used for customising the screen labels when using the Screen Wizard.

#### Copying specific parameter sets

When you have saved a number of parameter sets to an IOP-2, it is possible to copy your saved parameter sets to another IOP-2 using the simple process outlined below.

- 1. Connect the IOP-2 via the USB connector to a PC.
- 2. The IOP-2 will enter the "Mass Storage Device" Mode.
- 3. On the PC, navigate to the "user/cps" folder.
- 4. Select the parameter sets you require and save them to a new folder on the local drive of the PC.
- 5. Disconnect the IOP-2 from the PC.
- 6. Connect another IOP-2 and copy the saved parameter sets to the "user/cps" on the new IOP-2.

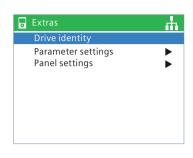
This procedure can be repeated for any number of IOP-2s.

8.8 Extras Menu

# 8.8 Extras Menu

## Overview

The Extras menu presents a number of options for the configuration of the IOP-2, these are explained in this section.



## **Drive identity**

This option allows the user to display the technical details of the components that comprise the converter system. This includes the details of the Control Unit and Power Module. This is a read-only screen and cannot be modified.

R	Drive identity	
Si Cl M SF	namics G120 BT J230P-2 BT LFB: 6SL3243-6BB30-1HA2 P. DB. Version : 04.70.83.00 J. FW. Version : 04.70.83	
Х	ESC	

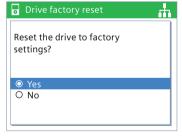
## **Parameter settings**

### Drive factory reset

There are two factory reset options:

*Factory reset* - This option resets all parameters to their factory default settings. Any safety parameters that have been modified will not be reset.

Safety factory reset - This option resets all the safety parameters back to the factory default settings. No other parameters will be changed.



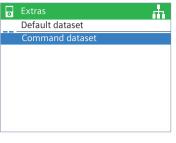
## Default dataset

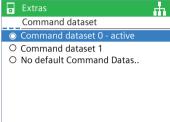
This option allows the user to determine which is the default command dataset when viewing or selecting a new default dataset from the options provided.

#### Note:

Some applications require that both command datasets be used at the same time. On the IOP-2 to access the parameters for both command datasets, then the command datasets screen must be set to "No default Command Dataset".

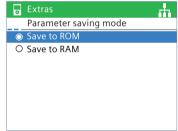
If the IOP-2 is not set to "No default Command Dataset" then only one command dataset will be visible to the IOP-2 in the parameter settings.





#### Parameter saving mode

This option allows the user to set the default location for any save function performed on the converter.



#### Save RAM to ROM

This option allows the user to manually save all drive data from the converters internal memory to the internal non-volatile memory - allowing the data to be retained until it is overwritten.

5 Save RAM to ROM	ф
Save drive RAM to ROM?	
Yes	
No	

## **Panel settings**

#### Language

This option allows the user to select the language that will be used to display information and text on the IOP-2. This option has been previously described in the initial set-up section of this manual.

For details of selecting this function see [] Initial set-up (Page 20)

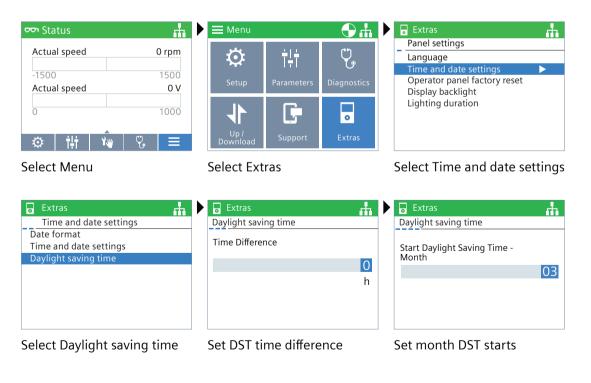
. E	xtras
L	anguage
0	English
0	Български
0	中文(简体)
0	Ceština
0	Deutsch
0	Suomi
0	Français

## Time and date settings (including Daylight saving time)

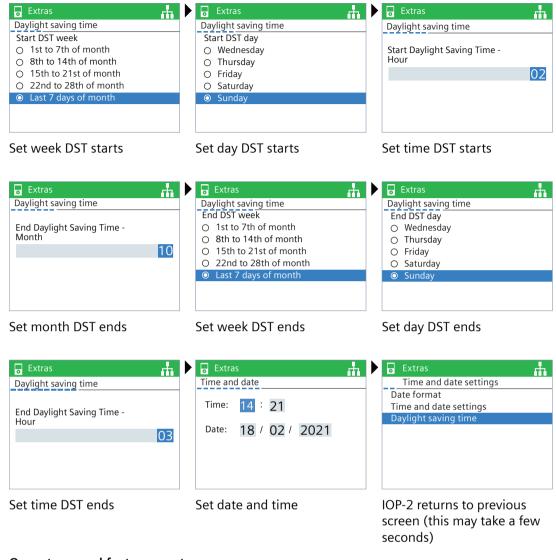
If the CU to which the IOP-2 is fitted has a real-time clock, then the option to set the correct date and time (including daylight saving time) is presented in the "Panel settings" menu.

The Time and date settings allow you to setup up the following:

- Date format- This allows the date format to be select either DD/MM/YY or MM/DD/YY.
- **Time and date settings** This allows the user to set the required date and time of the internal real-time clock of the Control Unit.
- **Daylight saving time** This allows the user to setup the daylight saving time difference on the Control Unit (CU230P-2) real-time clock. The daylight saving time is set to take into account not only the time difference but also the date and time of the change to and from daylight saving time. The setup of the DST function is shown in the following procedure.



#### 8.8 Extras Menu



## Operator panel factory reset

This option resets the IOP-2 to its default factory settings. All previous settings stored on the IOP-2 will be lost. Any parameter sets stored on the IOP-2 will not be deleted.

Operator panel factory reset	ф
Reset the operator panel to factory settings?	
Yes	
No	

8.8 Extras Menu

## **Display backlight**

This option allows the user to change intensity of the display lighting.

For details of selecting this function see [] Initial set-up (Page 20)

o Extras	<b>d</b> h
Display backlight	
O Very high	
O Medium	
O Low	
O Very Low	

## **Lighting duration**

The backlight display, by default, is set to automatically dim after 60 seconds from the last key press. This time can be adjusted to 30 seconds, 60 seconds, 300 seconds or permanently on.

For details of selecting this function see [] Initial set-up (Page 20)

### **Panel identity**

The panel identity screen displays the following technical information regarding the IOP-2:

- IOP-2 firmware version
- Bootloader version
- menu description version
- Parameter description version
- Menu texts version
- Parameter name index version
- Wizard description version.

Extras	ф
Lighting duration	
O 30 secs	
◎ 60 secs	
O 300 secs	
<ul> <li>Always on</li> </ul>	

Extras	di la
Panel identity	
IOP firmware: 02.03.00.00.21	
Bootloader: 01.00.36.00	
Menu description: 01.60.00.00	
Parameter description: 04.73.83.00	
English	
Menu name texts: 01.60.00.10	
Parameter name index: 04.73.83.00	
X ESC	

# Options

# 9.1 Door mounting kit

### Door mounting kit

The door mounting kit (DMK) has been designed to allow the IOP, IOP-2 or BOP-2 to be mounted into the door of a cabinet.

The Operator Panels (OP), when installed correctly in the door of the cabinet, provide the following IP ratings around the DMK:

- IOP: IP54
- IOP-2: IP55
- BOP-2: IP55

There are two types of mounting screws, one is designed for use with the brass insert on the back of the OP and the other is thread-forming screws which is to be used on the OP without the Brass inserts.

The fitting of the DMK is accomplished as shown in the figures below.

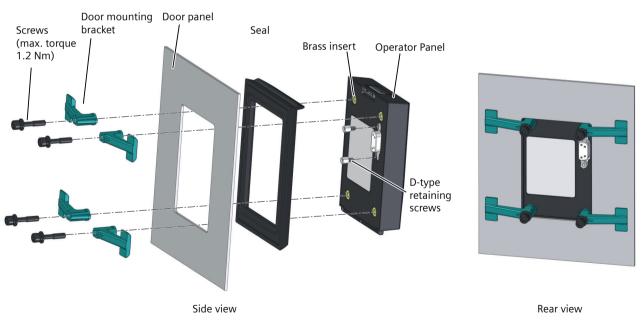


Figure 9-1 Fitting Operator Panel (brass inserts)

#### Options

## 9.1 Door mounting kit

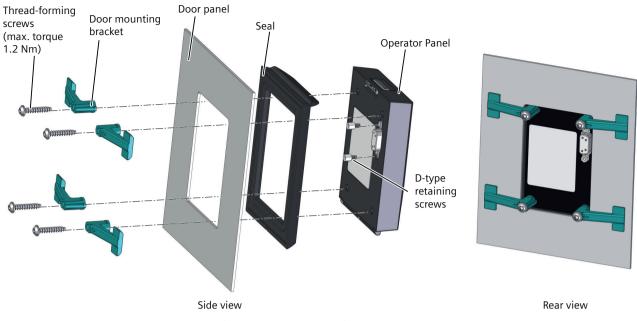


Figure 9-2 Fitting Operator Panel DMK (thread-forming screws)

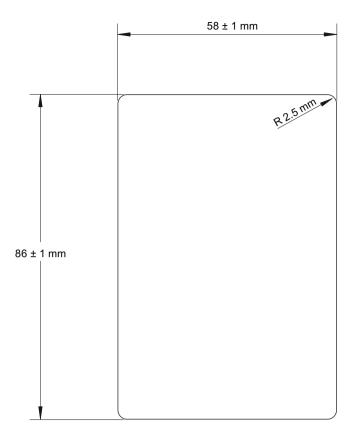
## CAUTION

#### Thread-forming screws maximum torques

Using a torque greater than 1.2 Nm with the thread-forming screws may lead to permanent damage of the threads. The thread-forming screws must be correctly aligned with the holes on the back of the OP; the thread-forming screws must not be used with the OPs with the brass inserts.

Prior to the installation of the DMK, it is necessary to create a hole in the panel or cabinet with the dimensions as shown in the figure below:

#### 9.1 Door mounting kit





#### Notes:

1. The page must be printed at full size to maintain the 1:1 scale.

2. When printing from a PDF file do not select the "fit to page" option as this will reduce the page to 97% of the true size.

The depth of the panel or cabinet door should be between 1 mm to 3 mm.

The IOP-2 Door Mounting Kit can be ordered using the following order number:

6SL3256-0AP00-0JA0

The DMK contains the following items:

- Door seal
- Door mounting brackets (x 4)
- Retaining screws (x 4)
- RS232 Straight-through cable (5 m)

9.2 Hand-held device

# 9.2 Hand-held device

## Hand-held device

## M WARNING

## Charging unit

- The charging unit for the rechargeable batteries is contained within the hand-held device for the sole purpose of charging rechargeable batteries.
- The charging unit contained within the hand-held device should not be used with standard "AA" batteries as this will result in damage to the batteries and the hand-held device.
- Only the supplied power supply unit should be used with the IOP-2. The use of any other power supply units could seriously damage the hand-held kit.

# 

## **General precautions**

- There is a risk of explosion if battery is replaced by incorrect type.
- Overcharging, short circuiting, reverse charging, mutilation, or incineration of the cells and the batteries must be avoided to prevent one or more of the following occurrences; release of toxic materials, release of hydrogen and/or oxygen gas, rise in surface temperature.
- If a cell or a battery has leaked or vented, it should be replaced immediately using protective gloves.
- If and when necessary, these cells or batteries must be replaced with identical new ones from the same manufacturer. If a cell or a battery to be replaced is connected with other cells or batteries in series, it is recommended that the other cells or batteries be replaced with new ones at the same time.
- Battery compartments containing these cells or batteries must be provided with means of ventilation to prevent possible accumulation of any released gases under abnormal conditions.

#### Note

#### **Battery lifetime**

With the supplied rechargeable batteries in a fully-charged state they should last for approximately 10 hours; the use of normal "AA" batteries may last considerably less time.

#### Industrial environment

The IOP-2 has been designed for use within a Class A Industrial environment only.

#### **Disposal of batteries**

The batteries supplied with the IOP-2 must be disposed of in accordance with local and national environmental policies.

#### Battery status

The battery status is displayed at the top right-hand corner of the IOP-2 display.

#### Battery charging

If the batteries are put on charge and the batteries are fully discharged; the charging unit will enter a 'pre-charge' state. During the pre-charge state the LED will not be lit, therefore there may be a delay before the charging LED lights up.

The IOP-2 has no internal power source, so to increase the IOP-2's versatility, the hand-held device has been designed.

The complete list of converters that work with the IOP-2 are listed in [] Introduction (Page 11). The following list comprises the converters that require the hand-held kit and the optical cable because the IOP-2 cannot be mounted directly on the converter:

- SINAMICS G120D-2 CU240D-2
- SINAMICS G120D-2 CU250D-2
- SINAMICS ET 200pro FC-2
- SINAMICS G110D
- SINAMICS G110M

Table 9-1Hand-held device order information

Order number	Item quantity	Item	Remarks
6SL3255-0AA00-4HA1	1	IOP-2	
	1	Hand-held module	
	1	Power supply unit	
	4	Rechargeable batteries	1.2 V 2100 mAh NiMH (see note below)
	1	RS232 cable	3 m

#### Note

## **Battery order information**

The batteries supplied with the IOP-2 Hand-held Kit should be replaced with exactly the same type of batteries. The batteries that have been tested for use with the IOP-2 are given below:

Company: GP Batteries

Order Number: GP210AAHC



The batteries can be ordered from the following website: GP Batteries (<u>https://uk.gpbatteries.com/products/recyko-aa-2100mah-rechargeable-battery-pack-of-4</u>)

The layout of the IOP-2 hand-held device is shown in the figure below.









Figure 9-3 IOP-2 Handheld kit layout

- 1. Intelligent Operator Panel (IOP-2)
- 2. IOP-2 release catch
- 3. ON/OFF switch
- 4. Charging LED ON when charging, OFF when charged
- 5. 9-pin Sub-D male connector (RS232)
- 6. Charging unit input

- 7. Battery compartment cover
- 8. IOP-2 retaining screw

## Fitting the batteries

The hand-held device is powered by four 'AA' rechargeable batteries; these batteries are supplied with the hand-held kit. The batteries are fitted as shown in the figure below.



Figure 9-4





Replace battery cover

Remove battery cover

Installing batteries for handheld kit

# Options

9.2 Hand-held device

# **Technical data**

# 10.1 Technical specifications

## **IOP-2-2** Technical data

Feature	IOP-2 only	Door mounting kit
Protection	Depending upon the Control Unit IP rating enclosure	to a max. of IP55 / UL Type 12
Dimensions (HxWxD)	106.86 mm x 70 mm x 19.65 mm	
Net weight	0.134 Kg (0.295 lbs)	
Gross weight	0.206 Kg (0.454 lbs) - includes packaging	
Screw torque	-	Max. 1 Nm to 1.25 Nm
Operating ambient tem-	0 - 50 °C (32 - 122 °F) when directly conne	ected to the converter.
perature	0 - 55 °C (32 - 131 °F) when using the Doo	r Mounting Kit.
Transport and storage ambient temperature	-40 - +70 °C (-40 - 158 °F)	
Humidity	Relative humidity <95% non-condensing	

Table 10-1 IOP-2 and Door mounting kit specifications

### Table 10-2 Hand-held specifications

Feature	IOP-2 Hand-held kit
Protection	IP20
Dimensions (HxWxD)	195.04 mm x 70 mm x 37.58 mm
Net weight	0.724 Kg (0.1.59 lbs)
Gross weight	0.970 Kg (2.14 lbs) - Inlcudes packaging
Operating ambient tem- perature	0 - 40 °C (32 - 104 °F) [charging 10 - 40 °C]
Transport and storage ambient temperature	-20 - +55 °C (-4 - 131 °F)
Humidity	Relative humidity <95% non-condensing

Technical data

10.1 Technical specifications

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# **Further Information**

Siemens: www.siemens.com

Industry Online Support (Service und Support): www.siemens.com/online-support

IndustryMall: www.siemens.com/industrymall

Siemens AG Digital Industries Motion Control Postfach 3180 91050 Erlangen Deutschland

> Scan the QR-Code for product information

