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Data sheet

6ES7512-1DM03-0AB0



SIMATIC DP, CPU 1512SP-1 PN for ET 200SP, central processing unit with work memory 400 KB for program and 2 MB for data, 1st interface: PROFINET IRT with 3-port switch, 25 ns bit performance, SIMATIC Memory Card required, BusAdapter required for port 1 and 2

Figure similar

General information	
Product type designation	CPU 1512SP-1 PN
HW functional status	FS03
Firmware version	V3.1
• FW update possible	Yes
Product function	
• I&M data	Yes; I&M0 to I&M3
 Module swapping during operation (hot swapping) 	Yes; Multi-hot swapping
Isochronous mode	Yes; only with PROFINET; with minimum OB 6x cycle of 500 µs
SysLog	Yes
Engineering with	
• STEP 7 TIA Portal configurable/integrated from version	V19 (FW V3.1) / V18 (FW V3.0) or higher; with older TIA Portal versions configurable as 6ES7 512-1DK01-0AB0
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	10 ms
Input current	
Current consumption (rated value)	0.48 A
Current consumption, max.	0.7 A
Inrush current, max.	1.34 A; Rated value
l ² ť	0.3 A ² ·s
Power	
Infeed power to the backplane bus	8.05 W
Power loss	
Power loss, typ.	3.5 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
 integrated (for program) 	400 kbyte
• integrated (for data)	2 Mbyte

Load memory	
	22 Chuto
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	No.
maintenance-free	Yes
CPU processing times	25
for bit operations, typ.	25 ns
for word operations, typ.	32 ns
for fixed point arithmetic, typ.	42 ns
for floating point arithmetic, typ.	170 ns
CPU-blocks	
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max. FB	1 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
Number range	0 65 535
• Size, max.	400 kbyte
FC	
Number range	0 65 535
• Size, max.	400 kbyte
OB	
• Size, max.	400 kbyte
Number of free cycle OBs	100
Number of time alarm OBs	20
Number of delay alarm OBs	20
Number of cyclic interrupt OBs	20; With minimum OB 3x cycle of 250 µs
	50
Number of process alarm OBs	
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	1
Number of technology synchronous alarm OBs	2
Number of startup OBs	100
 Number of asynchronous error OBs 	4
 Number of synchronous error OBs 	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
• Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	256 kbyte; in total; available retentive memory for bit memories, timers,
	counters, DBs, and technology data (axes): 216 KB
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	

Retentivity adjustable	Yes
Retentivity adjustable Retentivity preset	Yes
Retentivity preset Local data	NO
	C4 like the many 4C I/D man black
 per priority class, max. Address area 	64 kbyte; max. 16 KB per block
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	2 040, max. number of modules / submodules
Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	52 kbyte, All outputs are in the process image
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	0 KUYIC
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	0 KUYIC
Number of subprocess images, max.	32
Address space per module	02
Address space per module, max.	288 byte; For input and output data respectively
Address space per module, max.	
Address space per station, max.	2 560 byte; for central inputs and outputs; depending on configuration; 2 048
	bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	1
Number of IO Controllers	
integrated	1
• Via CM	0
Rack	
• Modules per rack, max.	82; CPU + 64 modules + server module (mounting width max. 1 m) + 16 ET 200AL modules
 Quantity of operable ET 200SP modules, max. 	64
 Quantity of operable ET 200AL modules, max. 	16
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Туре	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
• Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
supported	Yes
• to DP, master	Yes; Via CM DP module
• on DP, device	Yes; Via CM DP module
• in AS, master	Yes
• in AS, device	Yes
 on Ethernet via NTP 	Yes
Interfaces	
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1; Via CM DP module
Optical interface	No
1. Interface	
Interface types	
• RJ 45 (Ethernet)	Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45
Number of ports	3; 1. integr. + 2. via BusAdapter

integrated switch	Yes
BusAdapter (PROFINET)	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x M12, BA 2x FC, BA 2x LC, BA LC/RJ45, BA LC/FC, BA 2x SCRJ, BA SCRJ/RJ45, BA SCRJ/FC
Protocols	
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— Isochronous mode	Yes
— Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
- PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
— Of which IO devices with IRT, max.	64
- Number of connectable IO Devices for RT, max.	128
— of which in line, max.	128
 Number of IO Devices that can be simultaneously activated/deactivated, max. 	8; in total across all interfaces
 Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
— PROFINET Security Class	1
Update time for IRT	
— for send cycle of 250 μs	250 μs to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 μs of the isochronous OB is decisive
— for send cycle of 500 µs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
- for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
— With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 μs : 375 μs , 625 μs 3 875 $\mu s)$
Update time for RT	
— for send cycle of 250 µs	250 μs to 128 ms
— for send cycle of 500 µs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— Isochronous mode	No
— IRT	Yes
- PROFlenergy	Yes; per user program
— Shared device	Yes
— Number of IO Controllers with shared device, max.	4
- activation/deactivation of I-devices	Yes; per user program
— Asset management record	Yes; per user program
— PROFINET Security Class	SNMP Configuration and DCP Read Only
. Interface	
Interface types	
• RS 485	Yes; Via CM DP module
Number of ports	
Protocols	Vec
PROFIBUS DP master	Yes
PROFIBUS DP device	Yes
 SIMATIC communication 	Yes

PROFIBUS DP master	
Number of connections, max.	48; Of which 4 each reserved for ES and HMI
max. number of DP devices	125; In total, up to 512 distributed I/O devices can be connected via AS-i,
	PROFIBUS or PROFINET
Services	
— Equidistance	No
— Isochronous mode	No
- activation/deactivation of DP devices	Yes
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
Autonegotiation	Yes
Autocrossing	Yes
 Industrial Ethernet status LED 	Yes
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
 Number of connections, max. 	128; via integrated interfaces of the CPU and connected CPs / CMs
 Number of connections reserved for ES/HMI/web 	10
 Number of connections via integrated interfaces 	88
 Number of connections per CP/CM 	32
Number of S7 routing paths	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
— Media redundancy	Yes; only via BusAdapter
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
 MRP interconnection, supported 	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
 Switchover time on line break, typ. 	200 ms; For MRP, bumpless for MRPD
 Number of stations in the ring, max. 	50
SIMATIC communication	
 PG/OP communication 	Yes; encryption with TLS V1.3 pre-selected
S7 routing	Yes
 Data record routing 	Yes
 S7 communication, as server 	Yes
 S7 communication, as client 	Yes
 User data per job, max. 	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
— several passive connections per port, supported	Yes
ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes 2 khito: 1.472 hitos for LIDP broadcast
— Data length, max. — UDP multicast	2 kbyte; 1 472 bytes for UDP broadcast
ODP multicast ODPCP	Yes; max. 78 multicast circuits Yes
• DHCP • DNS	Yes
• DNS • SNMP	Yes
• DCP	Yes
• LLDP	Yes
ELDF Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
• web API	
— Number of sessions, max.	50

 number of simultaneous HTTP calls, max. 	4
— HTTP request body, max.	131 072 byte
OPC UA	
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call
- Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
- User authentication	"anonymous" or by user name & password
- Number of connections, max.	4
 — Number of nodes of the client interfaces, recommended max. 	1 000
 — Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_I max. 	300
 — Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
 — Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
 — Number of simultaneous calls of the client instructions for session management, per connection, max. 	1
 — Number of simultaneous calls of the client instructions for data access, per connection, max. 	5
- Number of registerable nodes, max.	5 000
 — Number of registerable method calls of OPC_UA_MethodCall, max. 	100
 — Number of inputs/outputs when calling OPC_UA_MethodCall, max. 	20
OPC UA Server	Yes; Data Access (Read, Write, Subscribe), Method Call, Alarms & Condition (A&C), Custom Address Space
 Application authentication 	Yes
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss
— User authentication	"anonymous" or by user name & password
 — GDS support (certificate management) 	Yes
 Number of sessions, max. 	32
 Number of accessible variables, max. 	50 000
 Number of registerable nodes, max. 	10 000
 Number of subscriptions per session, max. 	50
— Sampling interval, min.	100 ms
— Publishing interval, min.	200 ms
 — Number of server methods, max. 	20
 — Number of inputs/outputs per server method, max. 	20
 — Number of monitored items, recommended max. 	4 000; for 1 s sampling interval and 1 s send interval
- Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
 — Number of nodes for user-defined server interfaces, max. 	15 000
Alarms and Conditions	Yes
 — Number of program alarms 	100
 — Number of alarms for system diagnostics 	50
Further protocols	
MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
number of subscriptions, max.	250
number of tags/attributes for subscriptions, max.	2 000
Program alarms	Yes
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	5 000
Number of simultaneously active program alarms	
Number of program alarms	600
Number of alarms for system diagnostics	100

 Number of alarms for motion technology objects 	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Profiling	Yes
Status/control	
Status/control variable	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Number of variables, max.	
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
Forcing	Yes
Forcing, variables	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	200
• present	Yes
Number of entries, max.	1 000
- of which powerfail-proof	500
Traces	
Number of configurable Traces	4
C C	
 Memory size per trace, max. Interrupts/diagnostics/status information	512 kbyte
Diagnostics indication LED	Ver
• RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
Monitoring of the supply voltage (PWR-LED)	Yes
Connection display LINK TX/RX	Yes
Supported technology objects	
Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
 Number of available Motion Control resources for 	1 120
technology objects	
 Required Motion Control resources 	
— per speed-controlled axis	40
 per speed-controlled axis per positioning axis 	40 80
— per positioning axis	80
— per positioning axis — per synchronous axis	80 160
 per positioning axis per synchronous axis per external encoder 	80 160 80
 per positioning axis per synchronous axis per external encoder per output cam 	80 160 80 20
 per positioning axis per synchronous axis per external encoder per output cam per cam track 	80 160 80 20 160
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle 	80 160 80 20 160
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis 	80 160 80 20 160 40
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle 	80 160 80 20 160 40
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) 	80 160 80 20 160 40
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 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact 	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step 	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp 	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring 	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter 	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
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 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Ambient conditions 	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter Ambient conditions Ambient temperature during operation horizontal installation, min. 	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter Ambient temperature during operation horizontal installation, min. horizontal installation, max. 	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes

configuration / header		
configuration / programming / header		
Programming language		
— LAD	Yes	
— FBD	Yes	
— STL	Yes	
— SCL	Yes	
— CFC	Yes	
— GRAPH	Yes	
Know-how protection		
 User program protection/password protection 	Yes	
Copy protection	Yes	
Block protection	Yes	
Access protection		
 protection of confidential configuration data 	Yes	
 Protection level: Write protection 	Yes	
 Protection level: Read/write protection 	Yes	
 Protection level: Write protection for Failsafe 	No	
 Protection level: Complete protection 	Yes	
User administration	Yes; device-wide	
programming / cycle time monitoring / header		
lower limit	adjustable minimum cycle time	
upper limit	adjustable maximum cycle time	
Dimensions		
Width	100 mm	
Height	117 mm	
Depth	75 mm	
Weights		
Weight, approx.	265 g	
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